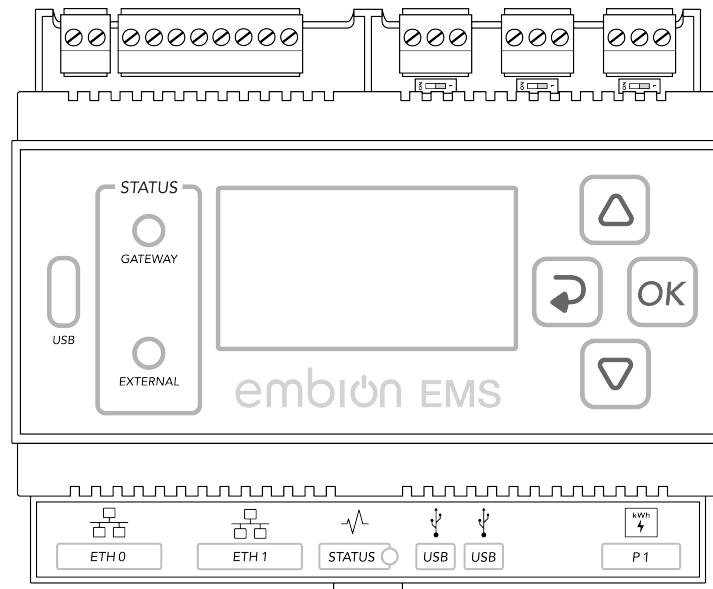


embion EMS

User Manual



embion

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Embion EMS Controller User Manual

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The Embion EMS Controller is designed for use in electrical systems, but it is not a safety device. It is the responsibility of the user to ensure that the system is properly equipped with the necessary safety measures to protect against any potential hazards. If the user is unsure about the safety requirements of their electrical system, they should consult with a qualified installer or distributor to determine what additional components or redundancy measures may be necessary. Embion B.V. cannot be held liable for any damages or injuries resulting from the use of the Embion EMS Controller without proper safety measures in place.

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Embion B.V. provides a limited warranty for the Embion EMS Controller (the "Product") to the original purchaser ("Purchaser") for a period of two (2) years from the date of purchase.

Embion B.V. warrants that the Product will be free from defects in materials and workmanship under normal use and service. If any defects in the Product occur during the warranty period, Embion B.V. will, at its sole option and cost, either repair or replace the defective Product or refund the purchase price paid by the Purchaser.

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To make a warranty claim, the Purchaser must provide proof of purchase and contact the reseller of the Embion EMS Controller. The reseller will provide instructions on how to return the defective Product and receive a replacement or refund.

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1 About this document

1.1 Purpose

This document introduces the Embion EMS Controller in terms of installation, electrical connections, system operation and maintenance and troubleshooting. Understand the Embion EMS Controller features, functions and safety precautions provided in this document before installing and operating the Embion EMS Controller.

To ensure an identical menu layout, please make sure that the version number of this document corresponds to the software release of the Embion EMS Controller.

 Note

This product has been renamed. Information in this document related to firmware versions below v5.0.0 also applies to the SolarGateway. Despite the name change, installation, configuration, and operating procedures remain unchanged. Features and integrations introduced in version 5.0.0 and later are not supported on the SolarGateway. To benefit from the latest features and integrations, upgrade your device to Embion EMS.

1.2 Intended Audience

This document is intended for operating personnel, system engineers adopting the Embion EMS Controller in their system design.

1.3 Symbol conventions

The symbols that may be found in this document are defined as follows:

 **Note**

Used for general notes in this documentation

 **Warning**

Used for expressing warnings in this documentation

 **Important**

Used for important notes in this documentation

 **Tip**

Used for general tips in this documentation

 **Caution**

Used for caution notes in this documentation

1.4 Change history

V5.2.4

Improvements:

- Fix for EPEX rules execution after license upgrade

01/29/2026

V5.2.3

Improvements:

- Fix for GPO readback
- Fix for EVBOX
- Fix for SG-ready

01/23/2026

V5.2.2

Improvements:

- Fix for Maxus V1 control

12/24/2025

V5.2.1

New features:

- Add support for both Maxus V1 and Maxus V2

Improvements:

- Fix for Growatt VPP battery control
- Fix for Ratio readout
- Fix for ABB PVS readout
- Fix for Acrel ACR10 and DTSD1352 readout
- Fix for battery power readout Faro
- Fix for SolaX Aelio control
- Improvements in IME EC protocols due to firmware inconsistencies across identical IME EC m

12/05/2025

V5.2.0

New features:

- Added support for scheduled plant control via API
- Added support for battery SoC control via API
- Added support for executing EPEX rules when offline
- Added support for Smappee AC chargers
- Added support for Smappee DC chargers
- Added support for Growatt VPP
- Added support for Ecotap
- Added support for RTI
- Added support for Zonbalans for Embion EMS
- Added support for FOX T-series

Improvements:

- Faster menu synchronization with HUB
- Improved control when the main meter(s) are unreachable
- Fix display names for several assets
- Added extra parameters for cascade

11/14/2025

V5.1.4

Improvements:

- Fix for hybrid inverter compatibility when using a PV-only licence
- Fix for P1 meter configuration as a load meter

12/16/2025

V5.1.3

Improvements:

- Fix for remote control SoC boundary

11/25/2025

V5.1.2

Improvements:

- Fix for battery and ev charger upload when no meter is configured
- Fix for compensate own consumption

11/11/2025

V5.1.1

Improvements:

- Minor improvements

10/23/2025

V5.1.0

New features:

- Added support for Growatt ShineMaster BESS
- Added support for QuSolar BESS
- Added support for Beny AC chargers
- Added support for 0-10V control of auxiliary devices (TBD)
- Added support for 40x scaling of P1 energy meter
- Added support for AccuPower BESS
- Added support for Dyness EMS
- Added support for go-e ev charger
- Added support for SolaX EMS Pro
- Added support for peergen PowerPeer
- Added support for Siemens PAC1665 7KT
- Added extra data for inverters, ev chargers and meters to use in HUB

Improvements:

- Improved menu synchronization with HUB
- Improved menu texts for control rules
- Improved Wi-Fi scan
- Improved EV charger control when controlled via API commands
- Improved Schneider Ecostruxure control

- Improved KStar control
- Improved communication after restarting controllable load.
- Improved grid current control
- Improved P1 meter readout
- Improved PowerStack control
- Improved GoodWe Hybrid readout

10/22/2025

V5.0.4

Improvements:

- Improvements in Gotion BESS control

09/09/2025

V5.0.3

Improvements:

- Deye control
- Minor updates

09/08/2025

V5.0.2

Improvements:

- Adding fast control selection option
- Improve Sofar G3 protocol
- Improvements in Sunspec protocols

08/29/2025

V5.0.1

Improvements:

- Improve Delta sunspec protocol
- Improve license selection

08/21/2025

V5.0.0

New features:

- Add support for ABB D11/D13
- Add support for ABB TMax
- Add support for Acrel ACR10
- Add support for AmpiTower
- Add support for Autel DC Charger
- Add support for Autel MaxiCharger AC-wallbox
- Add support for Beny DC Charger
- Add support for Cellpower 102-50
- Add support for Easee
- Add support for EcoBatt
- Add support for Elinex
- Add support for Faro
- Add support for Finder 7M24
- Add support for Finder 7M38
- Add support for Fudura Module
- Add support for Gotion BESS
- Add support for GridXense
- Add support for Hager Witty
- Add support for Joulz
- Add support for Kstar
- Add support for Nexblue
- Add support for Nidec DC Charger
- Add support for OX Energy B-OX L
- Add support for Ratio I07
- Add support for RCT CESS200
- Add support for SolaX X3 Mega
- Add support for Sungrow IDC 180E

Improvements:

- Improve battery and EV control speeds
- Improve EMS license selection
- Add Solis Hybrid V2 for all firmware support

08/11/2025

V4.7.1

Improvements:

- Improve PV reduction
- Improve PV reduction for Delta inverters
- Improve multi socket EV
- Improve multi solar meters readout
- Improve noise handling in EVBOX communication

06/23/2025

V4.7.0**New features:**

- Option to Compensate own usage with battery
- Adjustable data upload interval to preserve internet usage
- Add 15min power control
- Add feature to limit maximum PV limitation to 5%
- Add support for Boltainer BBT battery
- Add support for Peblar AC charger
- Add support for SMA hybrid
- Add support for Sungrow Powerstack
- Add support for Ferroamp hybrid inverter (no PV control)
- Add support for Fudura meter module
- Add support for Acrel ACR10 meter
- Add support for FlexiCharge AC chargers
- Add support for Sinexcel SEC240
- Add support for ABB D11/D13
- Add PV control for Deye HV (firmware version 1095 or newer)
- Add PV control for Solax X3 Ultra
- Add control for Eaton XStorage

Improvements:

- Preserve measurement data when device is offline
- Improved language selection process
- Better power calculation for offline devices
- Fix Solis hybrid battery power sign
- Improved Growatt V2 solar power calculation
- Improved Deye HV readout

05/15/2025

V4.6.0

New features:

- Add support for new license structure

Improvements:

- Changed support for FutureNED EV193 to battery

03/27/2025

V4.5.0

New features:

- Add support for Storion G2
- Add PV control for Sigenergy
- Add support for Chint DTSU666 (Gain) meter (see Appendix)
- Add support for Solax Aelio

Improvements:

- Allow discharge of battery by API while charge with grid return power is enabled
- Fix scaling issue grid phase 3 in modbus server
- Improve backup/restore of user settings and configuration

03/25/2025

V4.4.0

New features:

- Added support for FutureNED EV193 (only AC side charging power available)
- Added support for Aiswei (Solplanet) inverters
- Added support for Renepoly Parallel BESS systems
- Added support for Amtron Professional
- Added support for metertypes generator and wind

Improvements:

- Improved Modbus TCP speed
- Improvement for "Use PV for grid return power"

02/28/2025

V4.3.4

Improvements:

- Fix yield calculation for several inverters

02/24/2025

V4.3.3

Improvements:

- Fix Modbus server register offsets & reconnect-ability
- Improved PV control

02/18/2025

V4.3.2

Improvements:

- Correction for Cubenergy PowerCombo
- Allow multiple TCP ports for single IP and unit id

02/11/2025

V4.3.1

Improvements:

- Correct empty menu

02/07/2025

V4.3.0

New features:

- Added support for Sigenergy (no PV control, no total PV yield)
- Added support for Cubenergy PowerCombo

Improvements:

- Improved handling for offline devices
- Fix in Modbus server Holding Registers
- Fix for invalid values SMA datalogger

02/07/2025

V4.2.0**New features:**

- Added Modbus TCP server functionality
- Added support for FOX-ESS GMax
- Added support for Weiheng V2
- Added support for EVBox G4
- Added support to control Ctek charger (Firmware version r4.9 or newer)
- Added support for Kempower DC charger (no total charged energy)

Improvements:

- Correction for SolaX 3PH inverter
- Correction for Sungrow yield readout
- Name change Myrtillo to eCactus TH Hybrid

02/04/2025

V4.1.0**New features:**

- Added support for SolaX X3 Ultra
- Added support for Studer Next3
- Added support for Myrtillo battery (No Solar control)
- Added controllable load as Auxiliary device
- Added support for Schneider EVLink Pro AC (Software version 1.2.1 and newer)

Improvements:

- Improved battery power controller

01/08/2025

V4.0.0

New features:

- Added auto correction on negative grid settings
- Added mloea tap function
- Added support for solar meter
- Added update configuration settings using HUB
- Added support feature through HUB
- Added Wi-Fi signal strength to HUB

Improvements:

- Adjusted Wi-Fi network list order
- Updated welcome screen for new installations

12/12/2024

V3.6.1

Improvements:

- Solved issue where some inverters did not upload its yield data
- Modbus stability improved

11/12/2024

V3.6.0

New features:

- Wi-Fi functionality
- Support for ALP-EV, Vestel and Amtron EV chargers
- Support for Siemens PAC2200 7km and Schneider PM8000 series energy meter
- Support for Chint solar inverters
- Support for Cellpower battery system
- Improved daily yield calculations
- Automatic license activation

Improvements:

- Improve Huawei Hybrid communication for multiple inverters

11/20/2024

V3.5.1 - Fix bug: inverters where not correctly configured. 10/28/2024

V3.5.0 - Optimization of EV charger control, exceptional issue with MLOEA configurations resolved, Add voltage readings for EV chargers. Improved upload of device data. Add Sofar Power Magic battery. Improve battery control. Add factory reset option. 10/16/2024

V3.4.0 - Add Victron battery system, add Autarco solar inverter, add ABL eM4 ev charger, add Phoenix EEM energy meter, improve Modbus stability. 8/21/2024

V3.3.1 - Fix total EV charger power calculation for Orbis chargers. Fix GPIO control when single is selected, while fields are not filled. 8/6/2024

V3.3.0 - Add support for Solax Trene battery and GoodWe-HT inverters, add support for Ctek ev charge (no power control). Automatically charge battery when SoC drops below minimum SoC. Add optional controller for PV release for import limit during min-generation. Add support for GPIO control on summed load meters, battery power and PRIO. Fix problem for controlling multiple batteries. 8/2/2024

V3.2.1 - Improve (weighted) SoC and summed (plant) battery power calculation. 7/16/2024

V3.2.0 - Allow "group control" for GPIO on external modules. Allow same Unit IDs on multiple TCP devices. Upload plant battery power and SoC and EV charger power. Add Fronius inverter, Deye HV battery inverter. Schneider IEM 3 phase and Inepro PRO380 energy meter added and correct IME Nemo EC readout. Fix Alfen energy readout. General improvements. 7/15/2024

V3.1.2 - Fix issue with Solax inverters, fix powerfactor scaling for IME NEMO energy meter. 6/18/2024

V3.1.1 - Fix issue with Huawei Bess and OX power battery 6/6/2024

V3.1.0 - Add Weiheng battery, fix Deye maximum strings, change device list to alphabetical order. 5/29/2024

V3.0.0 - Internal system architecture upgrade. Add OX Energy B-OX XL battery system, add IME Nemo EC energy meter. Allow configurable scale factor for P1 energy meter. 5/17/2024

V2.14.2 - Fix gridpower upload to HUB portal. 4/18/2024

V2.14.1 - Improve counter strategy, fix enable reduction problem for Sungrow inverters. 4/16/2024

V2.14.0 - Add Huawei Hybrid inverter, GoodWe Hybrid and Maxus battery. Add Diris B10 and IME Conto energy meter. Fix scaling for ABB B23/B24. 4/8/2024

V2.13.0 - Add Huawei SL BESS system, make difference for Chint DTSU666 (series and normal). Add support for Ratio EV charger. Add Afore HV for HV battery systems. Add Safety margin option for active power control. 3/8/2024

V2.12.0 - Add battery SoC control. Fix error messages. Fix Schneider IEM 1 phase energy meter exported energy readout. General bugfixes. 2/13/2024

V2.11.0 - Add support for GoodWe and GoodWe-MT inverter, fix large AC power values for ABB PVS during the night. 1/24/2024

V2.10.0 - Add support for Megarevo hybrid inverter, Sungrow inverter and Schneider IEM 1 phase energy meter. Further improve battery control. Allow control for 1 phase grid connections. Fix minor bugs. 1/19/2024

V2.9.0 - Add support for battery control. Add support for Solis hybrid, Boltainer battery, Pixii battery, Ferroamp and Afore hybrid. Add support for IME Nemo, Mbus gateway and CarloGavazzi energy meters. Fix scaling with Janitza energy meter. 1/2/2024

V2.8.1 - General bugfixes and stability improvements. 12/12/2023

V2.8.0 - Add support for Zeversolar and Solis inverters, rebrand counter to Zonbalans with new spec. Add specific error messages for strategy. Allow autonomous update from selected track. 12/1/2023

V2.7.1 - Network static fix, ABB M4M IL2 fix 11/3/2023

V2.7.0 - Add support for Schneider 7KT, Huawei SL meter and ABB M4M energy meters. 11/2/2023

V2.6.1 - Fix EV charge control without inverters, Fix Eastron power factor readout. 10/27/2023

V2.6.0 - Add support for Altilia, Eaton Xstorage, Deye and Sofar G3 Hybrid inverters and Chint DTSU666 energy meter. Fix TCP IP configuration. 09/29/2023

V2.5.0 - Add ABB PVS inverter. Bugfix for GPO configuration in general template. 09/20/2023

V2.4.0 - New limits for counter strategy. Allow prio select for controlled loads. Enable data compression on the portal connection to significantly reduce the required internet data. Minor changes and bug fixes. 09/11/2023

V2.3.0 - Add "low power limit" control for generic strategy. Improve Counter strategy with requirements Enexis. Add support for EV chargers. Minor changes. 08/15/2023

V2.2.1 - Add gridvoltage control, active power control and GPIO control. Update supported inverter list and ETH0 and ETH1 settings. Minor changes. 07/21/2023

V2.1.0 - Update disclaimer, add IP range configuration for inverter, meter EV charger and auxiliaries, add split solar and grid option for load meters, add MLOEA configuration for grid meter and add system language configuration. Added warranty information. 04/11/2023

V2.0.0 - First release of the user manual 03/10/2023

2 Safety information

2.1 General Safety

2.1.1 Statement

Before installing, operating or maintaining the equipment, read this document and observe all safety instructions on the equipment and in this document.

The "Warning", and "Caution" statements in this document do not cover all the safety instructions. They are only supplements to the safety instructions. Embion B.V. will not be liable for any consequence caused by the violation of general safety requirements.

Ensure that the equipment is used in environments that meet its design specifications. Otherwise, the equipment may become faulty, the resulting equipment malfunction, component damage, personal injuries, or property damage are not covered under the product warranty.

Follow local laws and regulations when installing, operating, or maintaining the equipment. The safety instructions in this document are only supplements to local laws and regulations.

Embion B.V. will not be liable for any consequences of the following circumstances:

- Operation beyond the conditions specified in this document
- Installation or use in environments which are not specified in relevant international or national standards
- Unauthorized modifications to the product, software or removal of the product warranty sticker
- Failure to follow the operation instructions and safety precautions on the product and in this document
- Equipment damage due to force majeure, such as earthquakes, fire, and storms
- Damage caused during transportation by the customer
- Storage conditions that do not meet the requirements specified in this document

2.1.2 General requirements

 **Warning**

Do not work with system power turned-on during installation

- After installing the equipment, remove idle packing materials such as cartons, foam, plastics, and cable ties from the equipment area
- In the case of a fire, immediately leave the building or the equipment area, and turn on the fire alarm bell or make an emergency call. Do not enter the building on fire in any case
- Do not scrawl, damage, or block any warning label on the equipment
- Tighten the screws using the correct tools when installing the equipment
- Understand the components and functioning of the system, the Embion EMS Controller and relevant local standards
- You shall not to reverse engineer, decompile, disassemble, adapt, add code to, or alter in any other way, the device software; research the internal implementation of the device; obtain the device software source code; infringe on Embion B.V.'s intellectual property; or disclose any performance test results related to the device software.

2.1.3 Personal safety

- If there is a probability of personal injury or equipment damage during operations on the equipment, immediately stop the operations, report the case to the supervisor, and take feasible protective measures.
- Use tools correctly to avoid hurting people or damaging the equipment

2.2 Personnel requirements

- Personnel who plan to install or maintain Embion B.V. equipment must receive thorough training, understand all necessary safety precautions, and be able to correctly perform all operations
- Personnel working with the Embion EMS Controller must have knowledge of IP-based networks, RS485 bus systems, Modbus and addressing, validation of energy measurements, and knowledge of the devices to which the Embion EMS Controller is connected. The exact required knowledge may vary depending on the installation and application

- Only qualified professionals or trained personnel are allowed to install, operate, and maintain the equipment
- Only qualified professionals are allowed to remove or acknowledge any safety lock or notification on the device
- Only professionals or authorized personnel are allowed to replace the equipment or components

i Note

- Professionals: personnel who are trained or experienced in equipment operations and are clear of the sources and degree of various potential hazards in equipment installation, operation, and maintenance. It is task of a professional to understand the working concept of the complete system. This is required to correctly configure the Embion EMS Controller
- Trained personnel: personnel who are technically trained, have required experience, are aware of possible hazards on themselves in certain operations, and are able to take protective measures to minimize the hazards on themselves and other people
- Operators: operation personnel who may come in contact with the equipment, except trained personnel and professionals

2.3 Electrical Safety

2.3.1 General

⚠ Warning

Before connecting cables, ensure that the equipment is intact. Otherwise, electric shocks or fire may occur.

- Ensure that all electrical connections comply with local electrical standards.
- Ensure that the cables you prepared meet local regulations.

2.3.2 Product power supply

 **Warning**

Do not connect or disconnect power cables with power on.

- Before making electrical connections, switch off the disconnector on the upstream,
- Before connecting a power cable, check that the label on the power cable is correct.
- If the equipment has multiple energized inputs, disconnect all the energized inputs before operating the equipment.

2.4 Installation environment requirements

- Ensure that the equipment is installed in a well ventilated environment.
- Ensure the environment temperature does not exceed the maximum allowed environment temperature.
- Do not expose the equipment to flammable or explosive gas or smoke. Do not perform any operation on the equipment in such environments.

2.5 Commissioning

When the equipment is powered on for the first time, ensure that professional personnel set parameters correctly. Incorrect settings may result in damage to subsystems connected to the Embion EMS Controller.

2.6 Maintenance and replacement

- Maintain the equipment with sufficient knowledge of this document and using proper tools and testing equipment.
- If the equipment is faulty, contact your dealer.
- The equipment can be powered on only after all faults are rectified. Failing to do so may escalate faults or damage the equipment.

2.7 Internet and offline Storage

When there is no connection with HUB the EMS will store its data locally for up to a month. This data will be uploaded to the HUB once the connection is restored, this can take up to 24 hours. If the connection is lost for longer than a month, data which is older than a month will not be stored.

3 Product overview

3.1 Model description

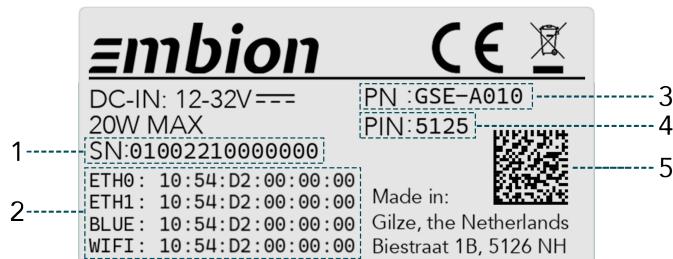
This document covers the following Embion EMS Controller models:

- EEC-A010
- GSE-A010
- GSE-A010-POE

3.2 Model identification

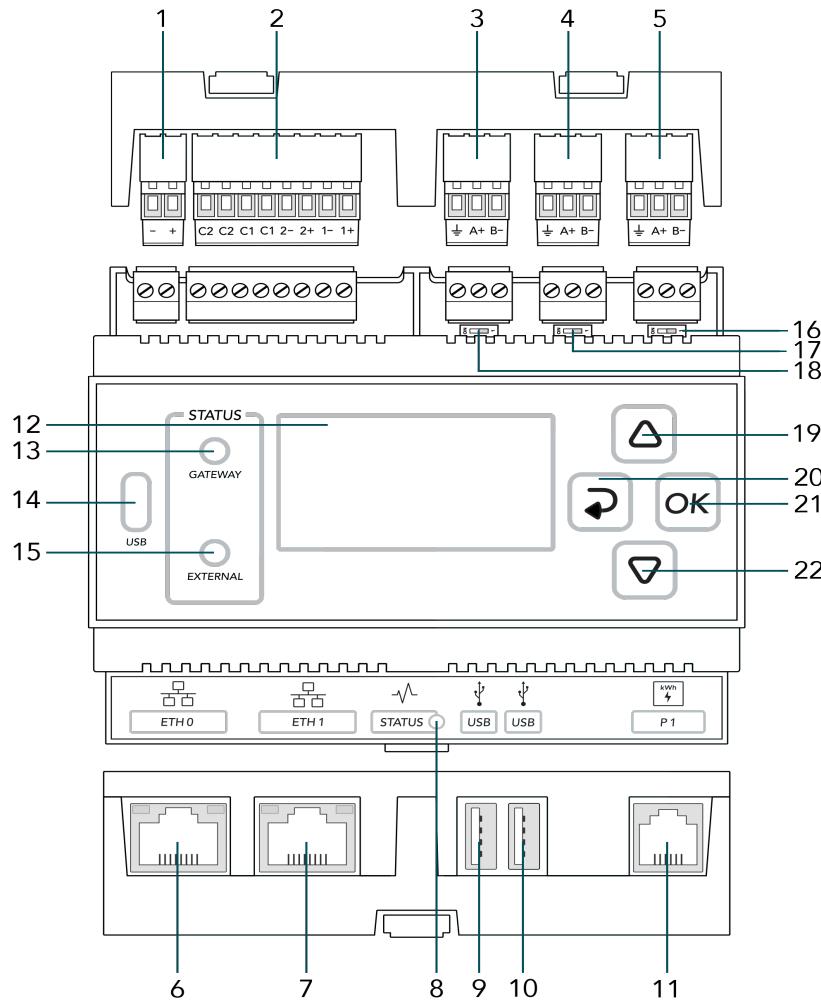
The model number of the Embion EMS Controller can be found on the label on the side of the device. The model number is listed on the label under PN (Product Name).

3.3 Label appearance



1. Serial Number
2. MAC Addresses
3. Product Name
4. PIN Code
5. Datamatrix

3.4 Product appearance



1. X14 DC Input Port	9. USB Port 0	17. X11 termination switch
2. X13 GPIO Port	10. USB Port 1	18. X12 termination switch
3. X12 RS485 Port C	11. P1 Port	19. Arrow up button
4. X11 RS485 Port B	12. LCD Screen	20. Back button
5. X10 RS485 Port A	13. EMS status LED	21. OK button
6. ETH Port 0 / POE	14. USB-C Port	22. Arrow down button
7. ETH Port 1	15. Service status LED	
8. Status LED	16. X10 termination switch	

3.5 Communication ports

3.5.1 X10 RS485 Default inverter port



The X10 RS485 connector is the default inverter port. It is possible to deviate from the default and use the port for something else as inverters.

X10 RS485 Connector			
Appearance	Pin Name		Description
	1	B-	RS485 Negative signal
	2	A+	RS485 Positive signal
	3	±	RS485 SHIELD (ISO GND)

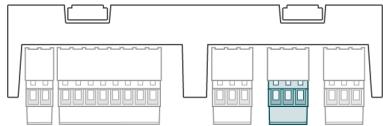
X10 120 ohm termination switch	
Position	Description
	Termination ON
	Termination OFF

The X10 120 ohm termination switch is used to terminate the the X10 RS485 bus.

! Important

The protocol and port settings (baudrate, parity databits and stopbits) need to be identical for all devices connected to the X10 port. Every (Modbus) slave address should be unique per port.

3.5.2 X11 RS485 Default meter port



The X11 RS485 connector is the default meter port. It is possible to deviate from the default and use the port for something else as meters.

X11 RS485 Connector			
Appearance	Pin Name		Description
	1	B-	RS485 Negative signal
	2	A+	RS485 Positive signal
	3	±	RS485 SHIELD (ISOGND)

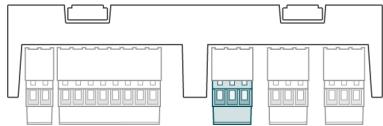
X11 120 ohm termination switch	
Position	Description
	Termination ON
	Termination OFF

The X11 120 ohm termination switch is used to terminate the the X11 port.

! Important

The protocol and port settings (baudrate, parity databits and stopbits) need to be identical for all devices connected to the X11 port. Every (Modbus) slave address should be unique per port.

3.5.3 X12 RS485 Default Auxiliaries port



The X12 RS485 connector is the default auxiliary devices port. It is possible to deviate from the default and use the port for something else as auxiliary devices.

X12 RS485 Connector			
Appearance	Pin Name		Description
	1	B-	RS485 Negative signal
	2	A+	RS485 Positive signal
	3	±	RS485 SHIELD (ISOGND)

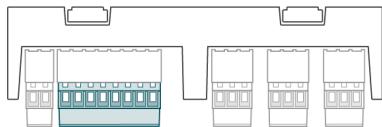
X12 120 ohm termination switch	
Position	Description
	Termination ON
	Termination OFF

The X12 120 ohm termination switch is used to terminate the the X12 port.

! Important

The protocol and port settings (baudrate, parity databits and stopbits) need to be identical for all devices connected to the X12 port. Every (Modbus) slave address should be unique per port.

3.5.4 X13 GPIO Port

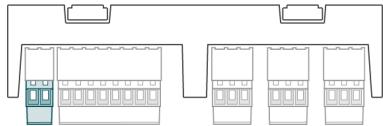


The X13 GPIO connector can be used for general input/output control.

X13 GPIO Port			
Appearance	Pin Name		Description
	1	1+	Potential free input #1 (+)
	2	1-	Potential free input #1 (-)
	3	2+	Potential free input #2 (+)
	4	2-	Potential free input #2 (-)
	5	C1	Potential free output contact #1
	6	C1	Potential free output contact #1
	7	C2	Potential free output contact #2
	8	C2	Potential free output contact #2

GPIO electrical specifications			
Item	Min	Max	Unit
Input 'low' voltage	-32.0	2.0	V
Input 'high' voltage	5.0	32.0	V
Input forward current	1.0	6.0	mA
Contact (C) switch voltage	-	32.0	V
Contact (C) switch current	-	2.0	A
GPIO isolation voltage	-	48.0	V

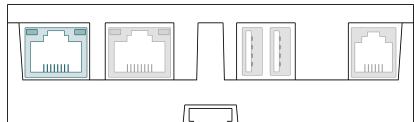
3.5.5 X14 DC Input Port



X14 DC Port			
Appear	Pin	Name	Description
	1	+	External DC power supply (+)
	2	-	External DC power supply (-)

DC input supply specifications			
Item	Min	Max	Unit
DC input voltage	12.0	32.0	V
DC input current	-	2.0	A
DC input power	-	20.0	W

3.5.6 ETH0 Port / POE



The ETH0 port can be used as normal Ethernet port and for powering the Embion EMS Controller with Power over Ethernet (POE) (only for the POE variants).

3.5.6.1 Port specifications

- 10/100/1000 Mbps

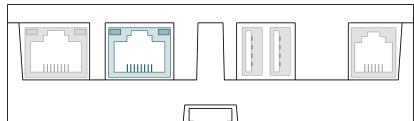
For the POE variant (PN: GSE-A010-POE):

- IEEE 802.3af PoE support (not recommended due to the power limit), device may reduce performance
- IEEE 802.3at PoE+ support
- Redundant power source possible, automatically switches between PoE and DC input. If both are present, PoE is preferred.

ETH0 Pinning	
Appearance	Pin Description
	1 BI_DA+
	2 BI_DA-
	3 BI_DB+
	4 BI_DC+
	5 BI_DC-
	6 BI_DB-
	7 BI_DD+
	8 BI_DD-

ETH0 Indicators	
Indicator	Description
Green	Blinks when data is transmitted/received
Yellow	On when POE+ source is connected

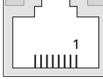
3.5.7 ETH1 Port



The ETH1 port can be used for ethernet connections on the Embion EMS Controller

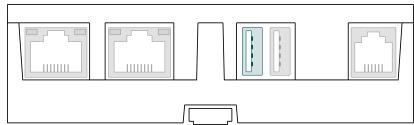
3.5.7.1 Port specifications

- 10/100 Mbps

ETH1 Pinning	
Appearance	Pin Description
	1 TX+
	2 TX-
	3 RX+
	4 NC
	5 NC
	6 RX-
	7 NC
	8 NC

ETH1 Indicators	
Indicator	Description
Green	Blinks when data is transmitted/received
Yellow	Reserved

3.5.8 USB0 Port



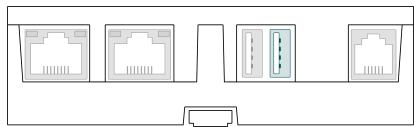
The USB0 port can be used to insert external storage devices into the Embion EMS Controller.

3.5.8.1 Port specifications

- Up to 500mA current delivery

USB0 Pinning		
Appearance	Pin	Description
	1	+5V
	2	D-
	3	D+
	4	GND

3.5.9 USB1 Port



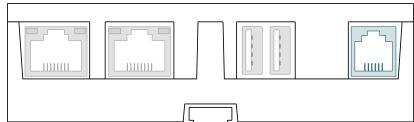
The USB1 port can be used to insert external storage devices into the Embion EMS Controller.

3.5.9.1 Port specifications

- Up to 500mA current delivery

USB1 Pinning		
Appearance	Pin	Description
	1	+5V
	2	D-
	3	D+
	4	GND

3.5.10 P1 Port



The P1 port is used to directly connect to a compatible smart meter.

3.5.10.1 Port specifications

- Reads meter directly from P1 connection on smart meter
- Support for DSMR 4.0-5.0
- Fixed baudrate of 115200 Baud
- Only usable for unencrypted meter data

⚠ Warning

Please make sure the meter connected to P1 is a DSMR 4 or DSMR 5 meter. Older DSMR versions are not supported at the moment.

P1 Pinning	
Appearance	Pin Description
 1	1 NC
	2 Data request
	3 ISOGND
	4 NC
	5 Data
	6 ISOGND

3.6 Status indicators

3.6.1 Status LED

Status LED		
LED	LED Status	Description
	Green	Device operational
	Red	System busy
	Blue	Reserved

3.6.2 Gateway LED

Gateway LED		
LED	LED Status	Description
	Green	Services are running
	Yellow	Problem with a service
	Red	Not operating

3.6.3 External LED

External LED		
LED	LED Status	Description
	Green	HUB control rules (energy pricing) active
	Cyan	Scheduled API control active
	Blue	Instantaneous API control active
	Purple	Remote support enabled

When multiple External LED statuses are active, they take precedence in the order shown above.

3.7 Buttons

3.7.1 UP Button

Button UP		
Appearance	Press	Action
	Short press	Short press action
	Long press	Long press action

3.7.2 DOWN Button

Button DOWN		
Appearance	Press	Action
	Short press	Short press action
	Long press	Long press action

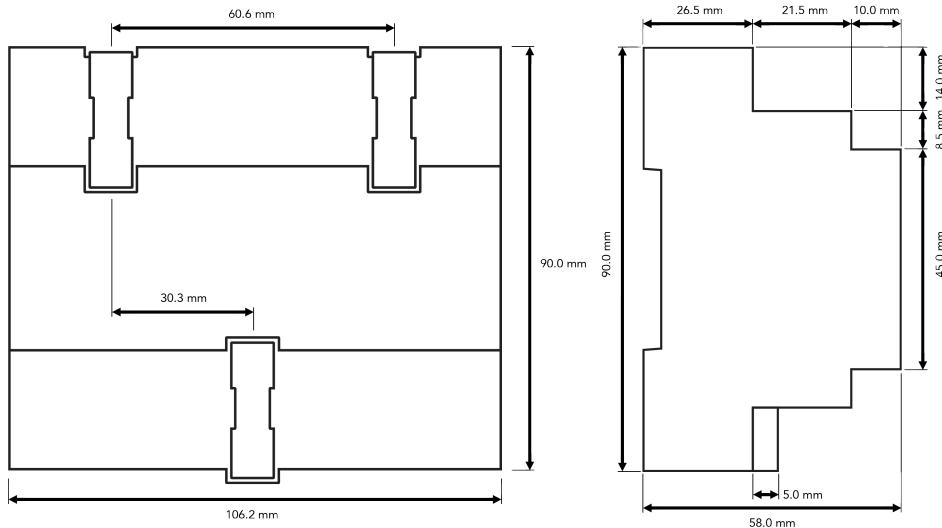
3.7.3 BACK Button

Button BACK		
Appearance	Press	Action
	Short press	Short press action
	Long press	Long press action

3.7.4 OK Button

Button OK		
Appearance	Press	Action
	Short press	Short press action
	Long press	Long press action

3.8 Dimensions



3.9 Weight

PN	Weight	Unit
GSE-A010	335	gram
GSE-A010-POE	355	gram
EEC-A010	335	gram

4 Device installation

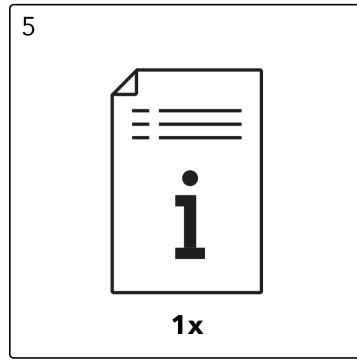
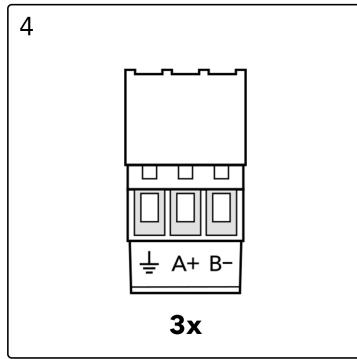
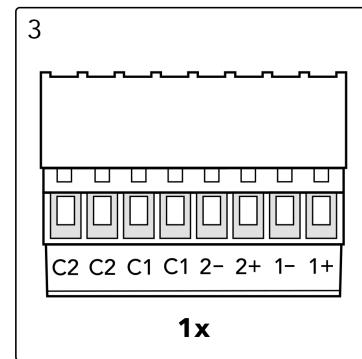
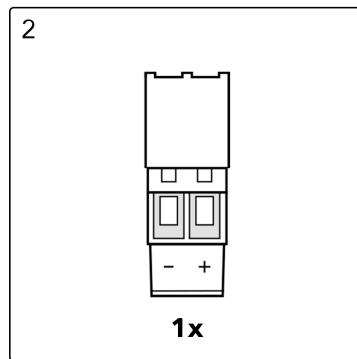
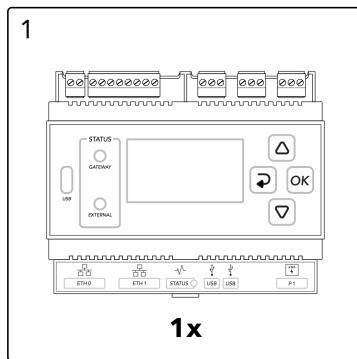
4.1 Box check

4.1.1 Outer packaging

Check if outer packaging is undamaged before opening it. If there are any signs of damage or abnormality, do not open the package and contact your dealer immediately.

4.1.2 Deliverables

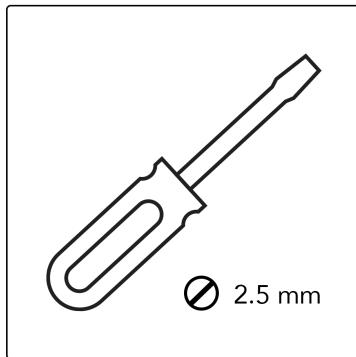
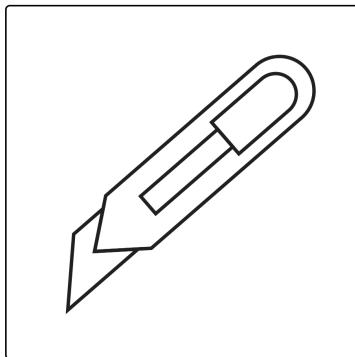
Check if the quantity against packing list is in the packing case. If any component is missing or damaged, contact your dealer.



Note

All provided connectors are already plugged into the device

4.2 Required tools



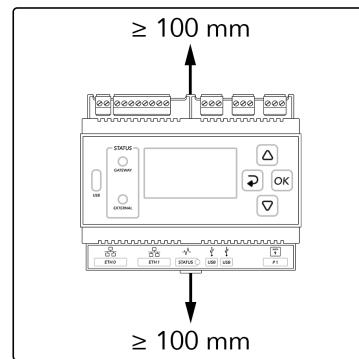
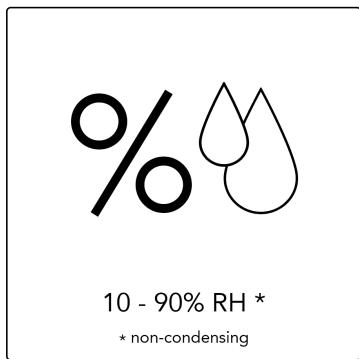
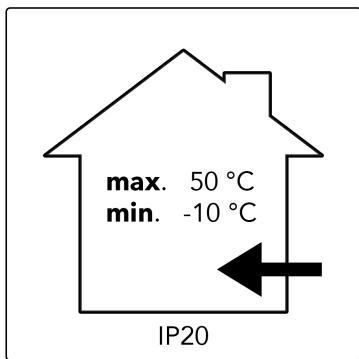
i Note

Depending on the specific type of installation and type of environment, extra tools may be required.

4.3 Installation Requirements

i Note

Proper installation of the Embion EMS Controller is essential for achieving optimum performance and ensuring easy maintenance. It is crucial to adhere to the recommended height to ensure optimal functionality. Additionally, it is important to meet the minimum object distance, ambient temperature, and humidity requirements to maintain the validity of the warranty. Failure to comply with these guidelines may result in voiding the warranty.



4.4 Installing the Embion EMS Controller

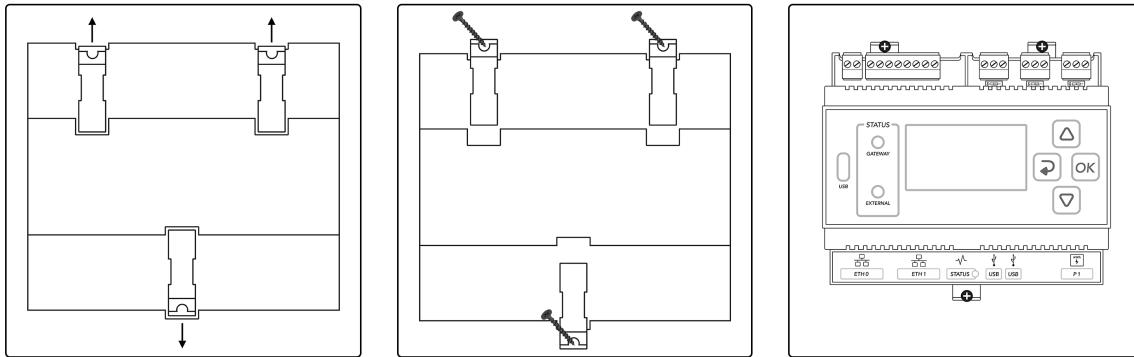
The Embion EMS Controller can be wall-mounted or DIN rail-mounted (preferred).

4.4.1 Wall-mounted installation

 **Warning**

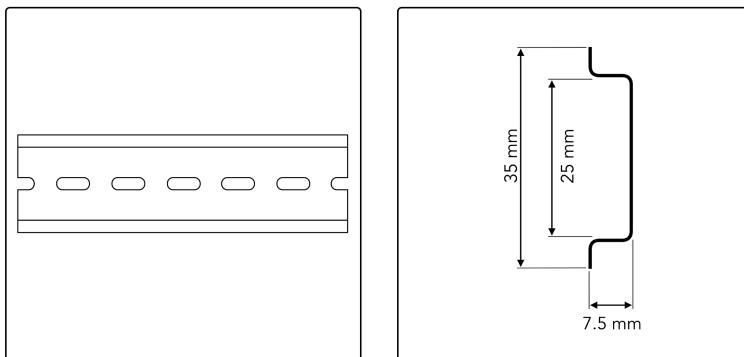
The Embion EMS Controller should be installed at a proper height to facilitate operation and maintenance

Install the Embion EMS Controller on a flat and secure wall



4.4.2 DIN rail mounted

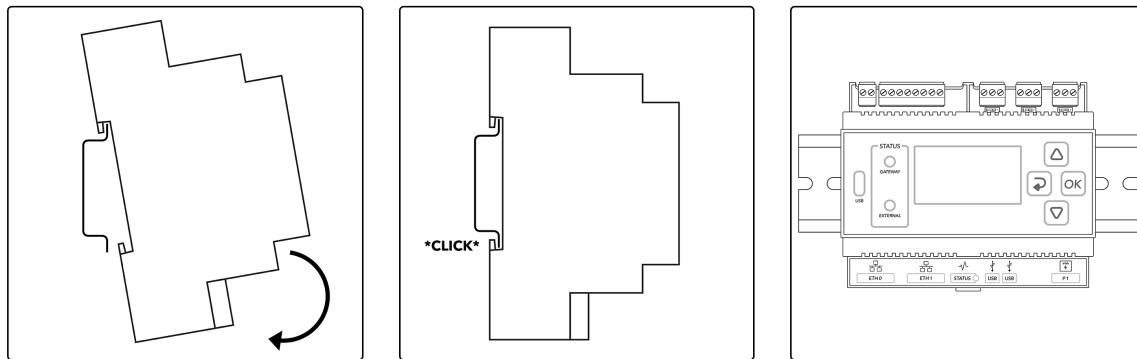
Prepare a 35mm standard DIN rail (not included). Ensure that the rail:



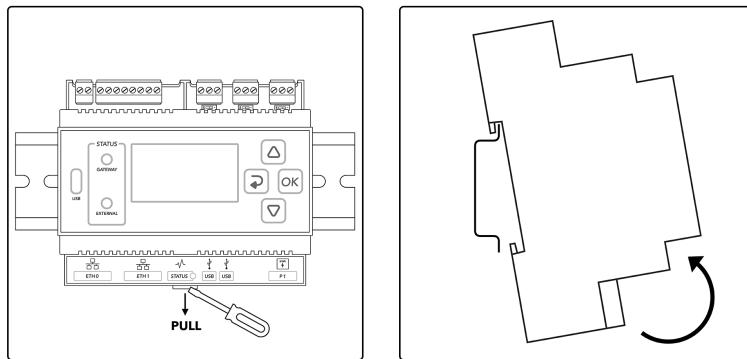
Ensure that the rail:

- Has sufficient length for securing the Embion EMS Controller. The recommended effective length is 120 mm or greater.
- Has been secured before you install the Embion EMS Controller.
- Is correctly terminated, so the Embion EMS Controller can't slide.

4.4.2.1 Attach to DIN rail



4.4.2.2 Remove from DIN rail



5 Device usage

5.1 Menu usage

The Embion EMS Controller device menu is used to configure the device. Multiple inputs are required during these settings. To allow for a standard and generic input option a dedicated input menu is designed. This menu allows for free character input, but it is important to understand the way of working as described in this chapter.

💡 Tip

The Embion EMS Controller also supports remote configuration via the HUB portal when the device is connected to the internet. After adding the device to a namespace, the user is able to setup the device though the HUB web interface.

5.1.1 Menu overview

The main page that is shown contains some general information about the installation. This page will automatically be shown when there is no more interaction between user and device. The items shown on this page may vary depending on the configuration. The dark bar shows actual system information.



5.1.2 Menu settings

When a menu page contains an arrow in the right corner, it means that there is a settings menu for it. Press the OK button to open the settings for the selected menu page. The images below show an example of the menu page "Modbus" which contains a settings menu "Modbus settings".



5.1.3 Menu pages

An overview of all the Embion EMS Controller menu pages with the related settings menu page is shown below. When a settings page is present, a reference to the related information page is given.

5.1.4 Device information



This page shows product information which is identical to the information on the product label. Also current software version is visible in this menu. Also the minimum and maximum internal measured temperatures (during lifetime) are shown here.

5.1.5 Config

This page will show the active strategy. For example: General. By entering the menu, strategy settings can be changed.



More information about the config settings can be found here: [Section 6](#)

5.1.6 Updates

This menu page shows the current update settings for the device. By entering the menu new device software can directly be installed if available.



More information about the update settings can be found here: Section [7.7](#)

5.1.7 System status

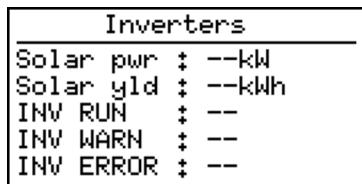
This menu page shows system status information. Internet connection, HUB setup and support information can directly be read from this page.



More information about the system status settings can be found here: Section [7.6](#)

5.1.8 Inverters

If any inverters are configured, this menu page(s) show the current status for all inverter(s) combined. The AC power per inverter is also listed. Depending on the number of inverters configured, multiple pages are used.



This menu page(s) displays the current status for each inverter. The displayed name of the inverter is the name of the group where it's in, combined with the inverter address. For

example the inverter "New 1.10" is a inverter from the inverter group "New 1" with the inverter address "10".

Inverters	
New 1.10	± --kW
New 1.11	± --kW
New 1.12	± --kW
New 1.13	± --kW
New 1.14	± --kW

Inverters	
New 1.15	± --kW
New 1.16	± --kW
New 1.17	± --kW
New 1.18	± --kW
New 1.19	± --kW

Inverters can be configured in the config settings for inverters explained on page: Section [6.3](#)

5.1.9 Meters

If any meters configured, this menu page(s) displays the current grid power and current status for each meter. The displayed name of the meter is the name of the group where it's in, combined with the meter address. For example the meter "New 1.10" is a meter from the meter group "New 1" with the meter address "10".

Meters	
New 1.10	± --kW
New 1.11	± --kW
New 1.12	± --kW
New 1.13	± --kW
New 1.14	± --kW

Meters	
New 1.15	± --kW
New 1.16	± --kW
New 1.17	± --kW
New 1.18	± --kW
New 1.19	± --kW

Meters can be configured in the config settings for meters explained on page: Section [6.4](#)

5.1.10 P1 Smart meter

This menu page displays the P1 smart meter status. No metering values are shown here, only connection related information.

P1 smart meter	
CONN:	--
ERRS:	--
ID:	--
VERS:	--
CLTS:	--

P1 can be configured in the config settings for meters explained on page: Section [6.4.2.1](#)

5.1.11 Modbus

This menu page displays the current Modbus status for all the RTU and TCP ports. The individual RTU ports can be configured through this menu.

Modbus	
RTU A	: --
RTU B	: --
RTU C	:Idle
TCP	:Idle

More information about the Modbus settings can be found here: Section [7.4](#)

5.1.12 Network ETH0

This menu displays the current ethernet status for the ETH0 connection.

Network ETH0	
IP	:192.168.1.77
NET	:255.255.240.0
GW	:192.168.0.1
DNS	:192.168.0.1
TYP	:DHCP

Network ETH0	
IP	: NET: GW: DNS: TYP: no link

More information about the ETH0 settings can be found on page: Section [7.1](#)

5.1.13 Network ETH1

This menu displays the current ethernet status for the ETH1 connection.

Network ETH1	
IP	:192.168.1.196
NET	:255.255.240.0
GW	:192.168.0.1
DNS	:192.168.0.1
TYP	:DHCP

Network ETH1	
IP	: NET: GW: DNS: TYP: no link

More information about the ETH1 settings can be found on page: Section [7.2](#)

5.1.14 Network Wi-Fi

This menu displays the current ethernet status for the Wi-Fi connection.



More information about the Wi-Fi settings can be found on page: Section [7.3](#)

5.1.15 GPIO

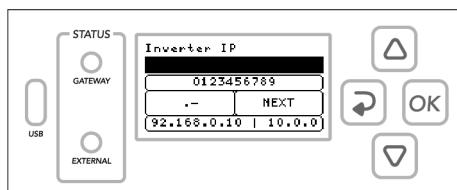
This menu page displays the GPIO status.



More information about the GPIO settings can be found on page: Section [7.5](#)

5.2 Input description

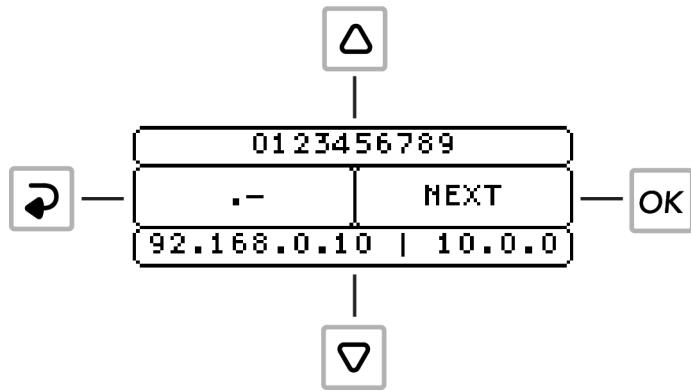
On the Embion EMS Controller there are multiple inputs required like IP addresses, IP address ranges and names. The steps below will explain how to use the buttons to insert characters.



5.2.1 Input options

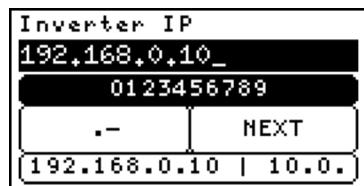
Use the buttons on the Embion EMS Controller to select one of the four input options related to the position of the pressed button.

For example: the UP button selects and highlight the numeric input.



5.2.2 Select characters

When an input option is selected, use the UP and DOWN buttons to navigate and select a character or pre-defined value like and IP-address. Press the OK button or wait 3 seconds to confirm the selected character or value. Characters now appear in the input field as shown below.



5.2.3 Remove characters

While one of the input option is selected, press the BACK button to remove the last character or hold the OK button to clear all input.

5.2.4 Uppercase

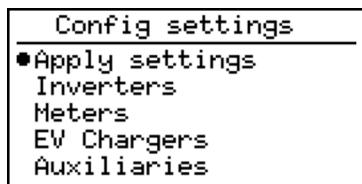
It is possible to use uppercase characters. Hold the UP button to activate uppercase characters, and hold it again to switch back.



6 Configuration settings

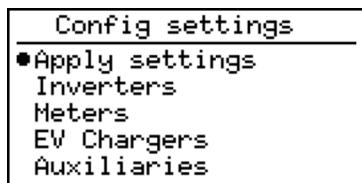
On the “Config settings” page the basic system settings are done. The following configuration item are found:

- Apply settings
- Grid settings
- Meters
- Inverters
- EV Chargers
- Auxiliaries
- Active power control
- GPIO control
- Grid voltage control
- Arc detection



6.1 Apply settings

All settings in the config menu can be changed without directly effecting the current function of the Embion EMS Controller. When settings are changed, the changes must by applied using this menu. Applying the settings can be done selecting one of multiple strategies. Each strategy has predefined controllers and certain required settings to be set. After applying a new strategy the system will check all requirements and only if all requirements for the strategy are met, the new strategy is applied.

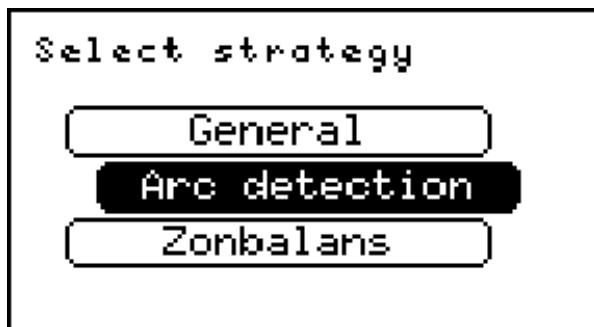


6.2 Activate config

This configuration will activate all settings for a selected strategy. Changed settings are stored, but not applied until the wanted strategy is selected and correctly applied. If a faulty configuration is found, the selected strategy returns an error, and the system function is not changed. Only if the selected strategy is correctly configured, the new configuration is applied and the old configured strategy is replaced by the new one.

6.2.1 Select strategy

To activate all settings, a strategy needs to be selected. The current implemented strategies are:



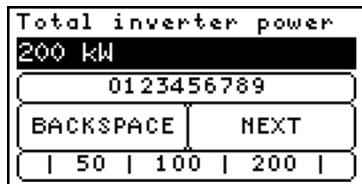
6.2.1.1 Zonbalans

Zonbalans will provide the stand-alone strategy using a grid meter, inverters and a pyrano sensor.

The maximum configured grid return power is used as maximum power. Until a measured radiation of $650 \frac{W}{m^2}$ the export limit is the configured grid return power. Between a measured radiation of $650 \frac{W}{m^2}$ and $975 \frac{W}{m^2}$ the export limit is linearly reduced from the configured grid return power to 0 kW. Therefore, at a measured radiation of $\geq 975 \frac{W}{m^2}$ the export limit is 0 kW.

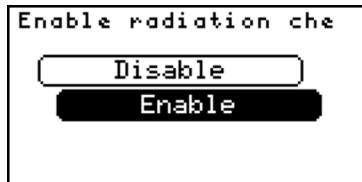
During the activation of the Zonbalans strategy, the total installed inverter power is requested. This is the sum of the AC output power of all connected inverters. This value is used for correct control of the power. For correct functioning of the Zonbalans strategy, please make sure the inverter power is correctly entered.

When activating the Zonbalans strategy all other control functions, like controlling GPIO, EV-chargers, battery converters etc. will be disabled.



The Embion EMS Controller is able to check the validity of the measured solar radiation, using the actual measured solar radiation and the actual solar power, combining both values using the total PV power configured in the inverter groups. When the generated solar power becomes larger than could be possible with the actual radiation and configured PV power, an error is triggered and the export limit is fixed to 0kW. The error can be recovered in the Zonbalans menu.

When the error is triggered it could indicate a dirty or not correctly functional radiation sensor and therefore wrong Zonbalans limits. If needed the check can be disabled while the Zonbalans strategy is applied.



6.2.1.2 Arc detection

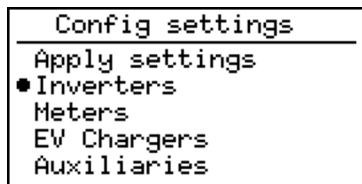
Arc detection will only provide the arc detection functionality using an external arc detection. This strategy will not implement any export or import limiter. This allows for easy and fast arc detection integration in existing systems.

6.2.1.3 General

General will provide all required controllers, except for the countering controller. This strategy uses the entered solar power per group and grid export limits to create (if required) an export controller. At least one grid meter is required to do so.

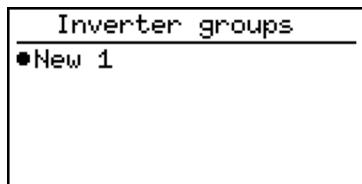
6.3 Inverter configuration

This configuration allows the user to configure the connected inverters (if any). multiple groups can be made, where each group connects to the same type of meters, through the same physical interface.



6.3.1 Inverter groups

The "Inverter groups" page will show all existing inverter groups. There is one pre-set group called "New 1" that isn't configured yet, this group is automatically added by removing your last existing group.



It is possible to add more groups, rename the existing groups, duplicate a specific group or delete one group. Select a group and hold the OK button to trigger this options.



6.3.2 Configure inverter group

The following inputs are required to configure a group of inverter(s):

- Inverter connection
- Address range
- Inverter type
- Inverter IP address
- Inverter TCP port
- Strings per inverter
- Total number of solar panels
- Peak power per panel

When the inverter has battery support, the following extra fields are required:

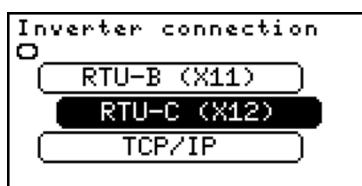
- Battery energy capacity (Capacity of battery, should be the same for all batteries in the group), used for weighted SoC average.
- Maximum active battery power
- Set charge prio
- Set discharge prio
- Minimum SOC (State of Charge)
- Maximum SOC
- Minimum SoC for remote control
- Maximum SoC for non-solar charge
- Minimum SoC for consumption compensation
- Allow automatic charge

i Note

Inverter IP and TCP port will only be asked when the selected connection type of the inverter is TCP/IP.

6.3.2.1 Inverter connection

Select the connection type of the to be configured inverter(s)



The following connection types can be selected:

- RTU-A (X10)
- RTU-B (X11)
- RTU-C (X12)
- TCP/IP

6.3.2.2 Inverter slave addresses

Insert the address range of the to be configured inverter(s). It is possible to separate addresses with the use of "," or to define a range with the use of "-". For example: The input "1,2,4-10" will set a address range from 1 to 10 except 3.

address range			
1,2,4-10			
0123456789			
-,	NEXT		
1-2	1-3	1-4	1,

i Note

An address may only occur once per RTU port. Meters and inverters could be connected to the same RTU port, as long as baudrate settings are identical and each connected slave has a unique address.

6.3.2.3 Inverter type

Select here the type or brand of the to be configured inverter.

Inverter type	
OO	Growatt-V2
Goodwe	
Huawei V2	
oooooooo	

The following types can be selected:

- ABB PVS
- ABB Trio
- AccuPower BESS
- Afore HV
- Afore LV
- Aiswei (Solplanet) [Aiswei configuration](#)
- Altilia
- AmpiTower
- Autarco
- Boltainer
- Cellpower
- Cellpower 102-50

- Chint
- Cubenergy PowerCombo
- Delta Sunspec
- Deye HV (firmware 1095 or newer)
- Dyness EMS
- eCactus TH Hybrid (No solar control)
- Eaton Xstorage
- EcoBatt
- Elinex
- Ferroamp
- Ferroamp Hybrid
- FOX-ESS GMax
- FOX T-series
- Faro
- Fronius (through datamanager (float32))
- FutureNED EV193 (can only charge battery of the charger)
- Gotion BESS
- GoodWe
- GoodWe-HT
- GoodWe Hyb
- GoodWe-MT
- Growatt ShineMaster
- Growatt-V1
- Growatt-V2
- Huawei Hybrid
- Huawei SL BESS
- Huawei V2
- Huawei V3
- INVT
- Kstar
- Maxus V1
- Maxus V2
- Megarevo
- OX Energy B-OX L
- OX Energy B-OX XL
- peergen PowerPeer
- Pixii
- QuSolar BESS
- RCT CESS200
- Renepoly Parallel
- SAJ Plus series
- Sigenergy (no total PV yield)
- SMA datalogger (only combined PAC, Yield and power control)

- SMA Hybrid
- SMA Sunspec
- SMA tripower
- SolaX 3phase
- SolaX EMS Pro
- SolaX Trene
- SolaX X3 Mega
- SolaX X3 Ultra Hybrid [Firmware requirements](#)
- SolarEdge
- Sofar G1
- Sofar G2
- Sofar G3
- Sofar G3 Hyb
- Sofar Power Magic
- Solis
- Solis Hyb
- Sungrow
- Sungrow PowerStack
- Studer Next3
- Victron BESS (using Cerbo GX via TCP)
- Weiheng
- Zeversolar

6.3.2.4 Inverter IP

Insert the IP address of the to be configured inverter(s). For example: "192.168.0.125".

It is possible to define multiple addresses in the address range and only one IP address if all addresses can be reached through the same TCP/IP slave.

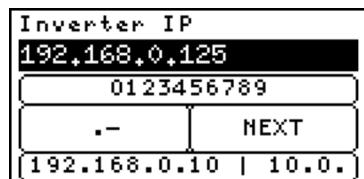
When the slaves are all reachable at the same address but on different IPs, it is possible to enter only one address and a range of IP addresses.

If each address has its own TCP/IP slave and a dedicated IP address, an IP range can be entered. To enter a range, the first IP address is entered followed by a ',' or a '-' and the last octet of the last IP address.

For example, if the address range is set to 1-4 (or 1, 2, 3, 4) and each address has a dedicated IP address, the IP input could be 192.168.0.10-13 (or 192.168.0.10, 11, 12, 13). The Embion EMS Controller will then translate this into the following IP addresses: 192.168.0.10, 192.168.0.11, 192.168.0.12, and 192.168.0.13.

i Note

It should be noted that when multiple IP addresses are defined, the number of defined addresses must be one or be equal to the number of defined IP addresses. Failure to meet this criteria will result in an error when the settings are applied.

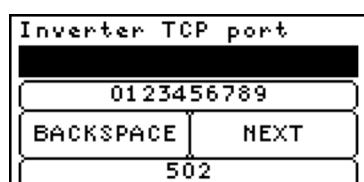


i Note

Inverter IP will only be asked when the inverter connection type is TCP/IP.

6.3.2.5 Inverter TCP port

Insert the TCP port of the to be configured inverter(s). For example: "502"



i Note

Inverter port will only be asked when the inverter connection type is TCP/IP.

6.3.2.6 Strings/MPPT per inverter

Insert the number of individual string or MPPT data which should be read for every inverter connected to the group. Basically the number of individually monitored strings or MPPTs per inverter is entered here.

Strings per inverter	
4	
0123456789	
BACKSPACE	NEXT
1 2 4 6 10	

6.3.2.7 Installed solar panels

Enter the total number of solar panels installed for this group of inverter(s).

Total number of panel:	
32	
0123456789	
BACKSPACE	NEXT
10 50 100 500	

6.3.2.8 Peak power per panel

Enter the peak power per panel for the installed solar panels. The total solar power (Installed solar panels * Peak power per panel) is used to calculate the required export limit controllers. If different panels are used, make sure the total entered power (Installed solar panels * Peak power per panel) is correct.

Peak power per panel	
200 Wp	
0123456789	
BACKSPACE	NEXT
200 300 400 45	

6.3.2.9 Enable active power control

If this setting is disabled the inverter is not controlled on active power. If needed some inverter groups can be excluded from the power control, while other groups have the control enabled.

⚠ Warning

The system controlled by the Embion EMS Controller should accept the control signal. To make this work, the external logger should be configured correctly. Active power control from the external logger should be disabled and the logger should accept external power control commands.

6.3.2.10 Maximum active battery power

This setting is only shown when a inverter with battery support is selected. The maximum active power of the battery can be entered. The Embion EMS Controller will limit the battery power setpoint to the configured value. The charge and discharge setpoints send to the battery will not exceed this value. The limit is applied per controlled battery. If multiple batteries are controlled per group, the limit is given per battery.

6.3.2.11 Battery energy capacity

The capacity of each battery. This capacity is used for the weighed SoC calculation. If multiple batteries are controlled within one group, the value is given per battery.

6.3.2.12 Set charge prio

Set the charge priority of the battery. When the priority is given free and the battery is allowed to charge, a charge setpoint is given to the battery. The charge priority should be lower (higher number) than the discharge priority.

6.3.2.13 Set discharge prio

Set the discharge priority of the battery. When the priority is not free yet, the discharge power will be maximum. Therefore the discharge can be used as peak shaving option to prevent exceeding the grid limits. The discharge prio should be higher (lower number) than the charge priority.

6.3.2.14 Minimum SoC

Set the minimum allowed SoC (State of Charge). When the SoC is reached the battery power setpoint will not allow any further discharge. If a SoC lower than the minimum SoC is measured, the battery is automatically charged with the configured charge prio, until the minimum SoC is reached.

6.3.2.15 Maximum SoC

Set the maximum allowed SoC (State of Charge). When the SoC is reached the battery power setpoint will not allow any further charge.

6.3.2.16 Minimum SoC for remote control

Minimum SoC to which the battery can be discharged via remote control. This value should be equal to or higher than "Minimum SoC". The difference is only used to compensate the grid import limit using the battery. When control generation is set to max via the public API or HUB the battery will discharge until this SoC is reached. When the battery is discharged due to grid limits which are remotely set (via public API or HUB), the discharge is not limited to this SoC.

6.3.2.17 Maximum SoC for non-solar charge

Maximum SoC for all charge actions, except negative grid power charge. The value should be equal or lower than "Maximum SoC", the difference can only be charged when "Charge with negative grid power" is enabled and the grid power becomes negative.

6.3.2.18 Minimum SoC for consumption compensation

The minimum SoC to which the battery can be discharged during own consumption compensation (function must be enabled in Active power control menu).

6.3.2.19 Allow automatic charge

When this setting is enabled, the battery will be given a charge setpoint as soon as the priority allows it. When it is disabled, the Embion EMS Controller will not automatically charge the battery, only if the consumption is set to maximum (or Charge battery with grid return power is enabled). If this function is used in combination with compensating own self-consumption, the "Maximum SoC for non-solar charge" must be at least 2% lower than the "Minimum SoC for consumption compensation".

6.4 Meter configuration

This configuration allows the user to configure the connected meters (if any). multiple groups can be made, where each group connects to the same type of meters, through the same physical interface.

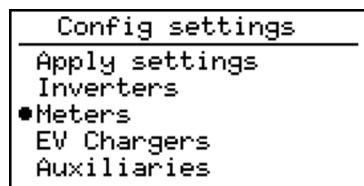
Note

Make sure the meter active power orientation is in the right convention used within the Embion EMS Controller.

A positive active power is always interpreted as a consumed power, while a negative active power is interpreted as a returned power.

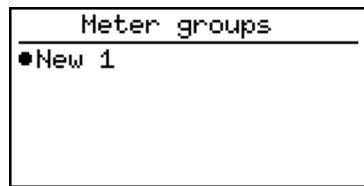
Warning

When peakshaving for PV generation is active, the active power orientation for the grid meter should be correct. The Embion EMS Controller is only limiting (on grid power or grid current) the connected inverters when the measured grid power is negative (returning power to the grid).



6.4.1 Meter groups

The "Meter groups" page will show all existing meter groups. There is one pre-set group called "New 1" that isn't configured yet, this group is automatically added by removing your last existing group.



It is possible to add more groups, rename the existing groups, duplicate a specific group or delete one group. Select a group and hold the OK button to trigger this options.



6.4.2 Configure meter group

The following inputs are required to configure a group of meter(s).

- Meter connection
- Address range
- Meter type
- Meter location
- Meter IP address
- Meter TCP port

i Note

Address range will only be asked when the selected connection type of the meter(s) is RTU or TCP/IP.

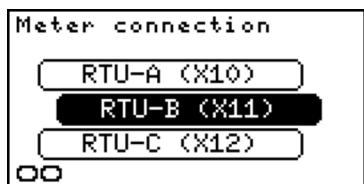
i Note

Meter IP address and TCP port will only be asked when the selected connection type of the meter(s) is TCP/IP.

6.4.2.1 Meter connection

Select the connection type of the to be configured meter(s) the options are:

- RTU-A (X10)
- RTU-B (X11)
- RTU-C (X12)
- P1
- TCP/IP



i Note

When meter(s) connection is P1, the only extra setting needed to complete are extra connected P1 meters and meter location.

6.4.2.2 Meter slave addresses

Insert the address range of the to be configured meter(s). It is possible to separate addresses with the use of "," or to define a range with the use of "-". For example: The input "1,2,4-10" will set a address range from 1 to 10 except 3.

Address range			
1,2,4-10			
0123456789			
-,	NEXT		
2	1-3	1-4	1,2,

i Note

An address may only occur once per RTU port. Meters and inverters could be connected to the same RTU port, as long as baudrate settings are identical and each connected slave has a unique address.

6.4.2.3 Meter type

Select here the type or brand of the to be configured meter. The following type or brands are available to select:

- ABB B23/B24 (No THD measurement)
- ABB D11/D13
- ABB TMax
- ABB M4M
- Acrel ACR10
- Anexo (Modbus converter)
- CarloGavazzi 1 phase (No THD measurement)
- CarloGavazzi 3 phase (No THD measurement)
- Chint DTSU666 [Chint DTS666 setup](#)
- Chint DTSU666 (no series)
- Chint DTSU666 (Gain) [Chint DTS666 setup](#)
- Eastron
- Finder 7M24
- Finder 7M38
- Fudura meter module
- GridXense
- Hager
- Huawei SL meter (energy meter connected to Huawei smartlogger) (No THD measurement)

- IME Conto (No THD measurement)
- IME Nemo
- IME Nemo EC
- IME Nemo EC corrected
- Inepro PRO380 (NO THD and line-line voltage measurement)
- Janitza
- Joulz
- Mbus gateway
- Phoenix EEM series
- Schneider IEM 1 phase (No THD measurement)
- Schneider IEM 3 phase
- Schneider NSX
- Schneider PM5000 series
- Schneider PM8000 series
- Siemens PAC1600 7KT (No THD measurement)
- Siemens PAC1665 7KT (No THD measurement)
- Siemens PAC2200 7KM (No THD measurement)
- Socomec Countis (No THD measurement)
- Socomec Diris A10
- Socomec Diris B10
- Weidemuller EM610



6.4.2.4 Meter IP

Insert the IP address of the to be configured meter(s). For example: "192.168.0.125".

It is possible to define multiple addresses in the address range and only one IP address if all addresses can be reached through the same TCP/IP slave.

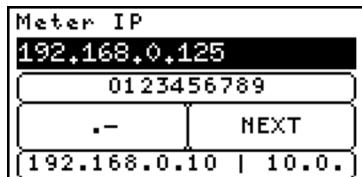
When the slaves are all reachable at the same address but on different IPs, it is possible to enter only one address and a range of IP addresses.

If each address has its own TCP/IP slave and a dedicated IP address, an IP range can be entered. To enter a range, the first IP address is entered followed by a ',' or a '-' and the last octet of the last IP address.

For example, if the address range is set to 1-4 (or 1, 2, 3, 4) and each address has a dedicated IP address, the IP input could be 192.168.0.10-13 (or 192.168.0.10, 11, 12, 13). The Embion EMS Controller will then translate this into the following IP addresses: 192.168.0.10, 192.168.0.11, 192.168.0.12, and 192.168.0.13.

i Note

It should be noted that when multiple IP addresses are defined, the number of defined addresses must be one or be equal to the number of defined IP addresses. Failure to meet this criteria will result in an error when the settings are applied.

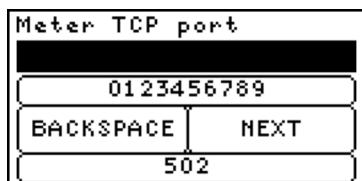


i Note

Meter(s) IP will only be asked when the meter(s) connection type is TCP/IP.

6.4.2.5 Meter TCP port

Insert the port of the to be configured meter(s). For example: "502"



i Note

Meter(s) port will only be asked when the meter(s) connection type is TCP/IP.

6.4.2.6 Meter location

Select here the meter(s) location of the to be configures meter(s), options are:

- Grid meter
- Load meter
- Solar meter
- Generator meter
- Wind meter
- MLOEA-PAP
- MLOEA-SAP
- MLOEA-TAP

i Note

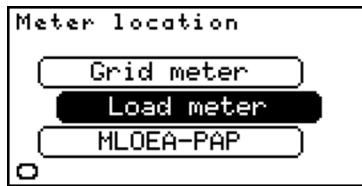
The Grid meter is used for control. To make sure the readout speed is not limited it is good practice to connect the Grid meter to a un-used port (RTU-A, RTU-B, RTU-C), and connect other devices to other ports. On this way the maximum readout speed is reached.

i Note

The solar, generator and wind meter can be used to measure power and energy flows from assets which can not be connected directly. The measurement direction should be the same as for consuming loads. Therefore the measured active power should be negative when there is generation.

i Note

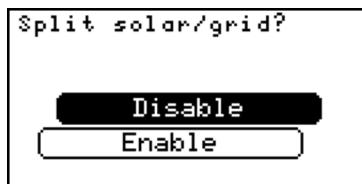
For a MLOEA grid connection, all meters (MLOEA-PAP, MLOEA-SAP and optionally the MLOEA-TAP) need to be configured. The Embion EMS Controller will calculate the actual grid power and currents by combining all meters. The MLOEA meters will replace the grid meter, configuring both will result in an incorrect configuration. Setting up only one of the minimum of two MLOEA meters result in an incorrect configuration.



6.4.2.7 Split solar/grid

Available when load meter is selected. Enabling this function will create two new meter registers, one for the energy directly consumed out of Solar energy and one register for the energy directly consumed out of grid energy. Two possible system configurations are possible.

- System with at least one grid meter and 1 or more load meters. The system will count all energy sourced by the grid meter as grid energy, all energy consumed but not sourced by the grid meter is counted as solar energy.
- System without a grid meter, in this case the power delivered by the connected solar inverters is used to calculate the solar energy. All other energy is counted as grid energy.



i Note

To activate the split solar/grid energy meters at least one grid meter or one solar inverter should be connected. An error is raised during setting activation when both (grid meter and solar inverter) are not configured.

6.4.2.8 Override scaling factor (only for P1 meter)

The values read from the P1 meter can be scaled with a fixed scaling factor. The default scaling factor is 1x. If "yes" is selected, the user will be prompted to enter the scale factor.

⚠ Warning

Only change the default scaling factor if this is required by the grid operator. Selecting the wrong value will result in inaccurate energy measurement and improper control of active power!

6.4.2.9 Scale factor

This option is only available when “Override scaling factor” is set to “yes.” Select the scale factor:

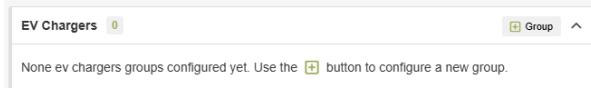
- 1x (default)
- 200x
- 500x
- 2000x

⚠ Warning

Ensure to verify the scaling factor. Selecting the wrong value will result in inaccurate energy measurement and improper control of active power!

6.5 EV Chargers

This configuration will define all EV Charger(s) settings.



6.5.1 EV Charger groups

The 'EV Charger groups' page will show all existing EV Charger groups. There is one pre-set group called 'New group' that isn't configured yet, this group is automatically added by removing your last existing group.



6.6 Note

When creating a group of EVChargers with type 'EVBox', only one group per RS485 port can be created.

i Note

When changing a group of EVChargers with type 'EVBox', the historical data of the EVBox chargers might become incorrect due to limitations of the EVBox protocol.

6.6.1 Configure EV Charger group

The following inputs are required to configure a group of EV Charger(s).

- EV Charger type
- EV Charger connection
- EV Charger slaves/zones
- EV Charger username
- EV Charger password
- Min. charge current
- Max. charge current
- Set prio
- EV Charger IP

6.6.1.1 EV Charger type

Select here the type or brand of the to be configured EV Charger(s). The following type or brands are available to select:

- ABB Terra
- ABL eM4 Controller [ABL eM4 configuration](#)
- Alfen
- Alp-EV EVC04
- Amtron TCP
- Amtron 4you RTU [Amtron 4you RTU configuration](#)
- Autel DC Charger
- Autel MaxiCharger AC-wallbox
- Beny AC Charger
- Beny DC Charger
- Ctek (Firmware version r4.9 or newer)
- Easee
- Etrel INCH
- EVBox G4
- Flexicharge AC [Flexicharge configuration](#)
- go-e EV Charger
- Hager Witty
- Kempower DC charger (no total charged energy)
- Nexblue
- Orbis
- Peclar
- Ratio Solar/IO6
- Ratio IO7
- Schneider EVLink Pro AC (Software version 1.2.1 and newer)

- Schneider EcoStruxure EV Charging Expert
- Sinexcel SEC240 (socket 1)
- Sinexcel SEC240 (socket 2)
- Smappee AC Charger
- Smappee DC Charger
- Vestel EVC04



6.6.1.2 EV Charger connection

Select the connection type of the to be configured EV Charger(s) the options are:

- RTU-A (X10)
- RTU-B (X11)
- RTU-C (X12)
- MODBUS TCP/IP
- REST API

i Note

When 'EV Charger type' is set to 'EVBox', the connection type options "RTU" are renamed to "RS485" and "Modbus TCP/IP", "REST API" are not available.



6.6.1.3 Amount of chargers

Enter the amount of EVBox chargers (both EVBox Hub and EVBox Satellite) connected to the the physical RS485 interface.

i Note

Amount of chargers will only be asked when the EV Charger(s) charger type is EVBox.

* Amount of chargers :

6.6.1.4 Amount of zones

Enter the amount of zones configured in the Schneider EcoStruxure EV Charging Expert

i Note

Amount of zones will only be asked when the EV Charger(s) charger type is "Schneider EcoStruxure EV Charging Expert".

* Amount of zones :

6.6.1.5 Amount of chargers per zone

Enter the amount of chargers added to single zone in the Schneider EcoStruxure EV Charging Expert. When multiple zones are configured, the amount of chargers per zone should be the maximum number of chargers per zone.

i Note

Amount of chargers will only be asked when the EV Charger(s) charger type is "Schneider EcoStruxure EV Charging Expert".

* Amount of chargers per zone :

6.6.1.6 EV Charger username

Enter the username of the to be configured EV Charger(s).

i Note

EV Charger(s) username will only be asked when the EV Charger(s) connection type is "REST API".

* Device username :

6.6.1.7 EV Charger password

Enter the password of the to be configured EV Charger(s).

i Note

EV Charger(s) password will only be asked when the EV Charger(s) connection type is "REST API".

* Device password :

6.6.1.8 EV Charger SN

Enter the SN of the to be configured EV Charger.

i Note

EV Charger SN will only be asked when the EV Charger type is "Easee" or "Nexblue".

* Device SN :

6.6.1.9 EV Charger slave addresses

Enter the slaves for the EV Charger(s). It is possible to separate slaves with the use of "," or to define a range with the use of "-". For example: The input "1,2,4-10" will set a the slaves 1 to 10 except 3.

i Note

EV Charger(s) slave addresses will only be asked when the EV Charger(s) connection type is "RTU-A", "RTU-B", "RTU-C" or "Modbus TCP/IP".

* Address range ⓘ :

6.6.1.10 Min. charge current

Select the minimum charge current which is send to the device during import limitation. If the current is more than 0, the charger will not stop charging, even if the configured import limit is exceeded. The configured minimum charge current should be equal to or less than Max. charge current.

* Min. charge current A :

6.6.1.11 Max. charge current

Select the maximum charge current which is send to the device when there is no import limit. The configured minimum charge current should be equal to or less than Max. charge current.

* Max. charge current A :

6.6.1.12 Set prio

The priority for the EV charger current can be set. When power for consumption is available, the Embion EMS Controller will increase loads depending on their priority. A high priority (low number) is released first and reduced last. Therefore, an EV charger with priority 1 always has the "Min. charge current" available, when the system limits allow it, the current is released to "Max. charge current". Any other EV charger with priority 2 or higher has the "Min. charge current" available, and will only increase the current if system limits allow it, and all chargers with a lower priority number are fully released.

Set prio:

 ▾

6.6.1.13 EV Charger IP

Insert the IP address of the to be configured EV Charger(s). For example: "192.168.0.125".

It is possible to define multiple addresses in the address range and only one IP address if all addresses can be reached through the same TCP/IP slave.

When the slaves are all reachable at the same address but on different IPs, it is possible to enter only one address and a range of IP addresses.

If each address has its own TCP/IP slave and a dedicated IP address, an IP range can be entered. To enter a range, the first IP address is entered followed by a ',' or a '-' and the last octet of the last IP address.

For example, if the address range is set to 1-4 (or 1, 2, 3, 4) and each address has a dedicated IP address, the IP input could be 192.168.0.10-13 (or 192.168.0.10, 11, 12, 13). The Embion EMS Controller will then translate this into the following IP addresses: 192.168.0.10, 192.168.0.11, 192.168.0.12, and 192.168.0.13.

i Note

EV Charger(s) IP will only be asked when the EV Charger(s) connection type is 'Modbus TCP/IP' or 'REST API'.

i Note

It should be noted that when multiple IP addresses are defined, the number of defined addresses must be one or be equal to the number of defined IP addresses. Failure to meet this criteria will result in an error when the settings are applied.

* Charger IP  :

6.6.1.14 Charger IP port

Insert the port of the to be configured EV Charger(s). For example: "502"

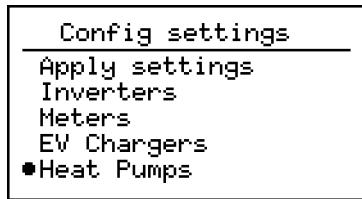
* Charger TCP port :

i Note

EV Charger(s) port will only be asked when the EV Charger(s) connection type is 'Modbus TCP/IP'.

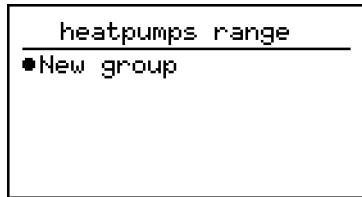
6.7 Heat Pumps

This configuration will define all Heat Pump settings.



6.7.1 Heat Pump groups

The 'Heat Pump groups' page will show all existing Heat Pump groups. There is one pre-set group called 'New group' that isn't configured yet, this group is automatically added by removing your last existing group.



It is possible to add more groups, rename the existing groups, duplicate a specific group or delete one group. Select a group and hold the OK button to trigger this options.



6.7.2 Configure Heat Pump group

The following inputs are required to configure a group of Heat Pump(s).

- Heat Pump connection
- SG Ready version
- Set prio

6.7.2.1 Heat Pump connection

Select the connection type of the to be configured Heat Pump(s) the options are:

- I/O (SG_ready)
- RTU-A (X10)
- RTU-B (X11)
- RTU-C (X12)
- TCP/IP



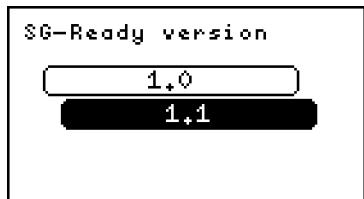
6.7.2.2 SG Ready version

Select the SG_ready version of the to be configured Heat Pump(s) the options are:

- Version 1.0
- Version 1.1

i Note

'SG Ready version' selection is only available when the Heat Pump connection type is set to "I/O (SG_ready)".



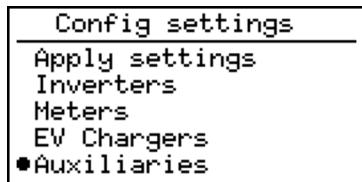
6.7.2.3 Set prio

The priority for the Heat Pump can be set. When power for consumption is available, the Embion EMS Controller will increase loads depending on their priority. A high priority (low number) is released first and reduced last.



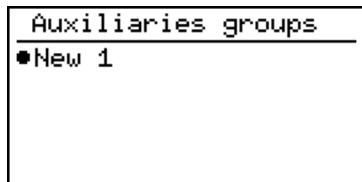
6.8 Auxiliaries

This configuration will define all Auxiliaries settings.



6.8.1 Auxiliaries groups

The 'Auxiliaries groups' page will show all existing Auxiliaries groups. There is one pre-set group called 'New group' that isn't configured yet, this group is automatically added by removing your last existing group.



It is possible to add more groups, rename the existing groups, duplicate a specific group or delete one group. Select a group and hold the OK button to trigger this options.



6.8.2 configure Auxiliaries group

The following inputs are required to configure a group of Auxiliaries:

- Auxiliaries connection
- Auxiliaries slaves
- Auxiliaries type
- Auxiliaries IP

6.8.2.1 Auxiliaries connection

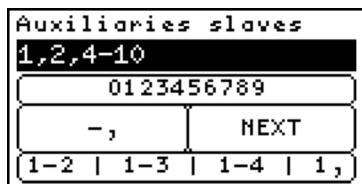
Select the connection type of the to be configured Auxiliaries the options are:

- RTU-A (X10)
- RTU-B (X11)
- RTU-C (X12)
- TCP/IP



6.8.2.2 Auxiliaries slave addresses

Enter the slaves for the Auxiliaries. It is possible to separate slaves with the use of "," or to define a range with the use of "-". For example: The input "1,2,4-10" will set a the slaves 1 to 10 except 3.



Note

An address may only occur once per RTU port. Slaves of different types could be connected to the same RTU port, as long as baudrate settings are identical and each connected slave has a unique address.

6.8.2.3 Auxiliaries type

Select the connection type of the to be configured Auxiliaries the options are:

- Controllable load
- IO TM-P4A4 (Modbus GPIO module)
- Kipp&Zonen SMP3-A (Pyrano sensor)
- Huawei SL pyrano (Pyrano sensor connected to the Huawei smartlogger)

6.8.2.4 Controllable load

For the controllable load function a configured load meter with the same groupname is required. The Embion EMS Controller will use the power from the load meter with the same groupname as load power and will calculate the extra available power. This power setpoint is written to the configured controllable load device.

i Note

If a pyrano sensor connected to the Huawei smartlogger is configured, use the configured pyrano sensor address configured in the smartlogger.



6.8.2.5 Auxiliaries IP

Insert the IP address of the to be configured Auxiliaries. For example: "192.168.0.125".

It is possible to define multiple addresses in the address range and only one IP address if all addresses can be reached through the same TCP/IP slave.

When the slaves are all reachable at the same address but on different IPs, it is possible to enter only one address and a range of IP addresses.

If each address has its own TCP/IP slave and a dedicated IP address, an IP range can be entered. To enter a range, the first IP address is entered followed by a ',' or a '-' and the last octet of the last IP address.

For example, if the address range is set to 1-4 (or 1, 2, 3, 4) and each address has a dedicated IP address, the IP input could be 192.168.0.10-13 (or 192.168.0.10, 11, 12, 13). The

Embion EMS Controller will then translate this into the following IP addresses: 192.168.0.10, 192.168.0.11, 192.168.0.12, and 192.168.0.13.

i Note

It should be noted that when multiple IP addresses are defined, the number of defined addresses must be one or be equal to the number of defined IP addresses. Failure to meet this criteria will result in an error when the settings are applied.

Auxiliaries IP	
192.168.0.125	
0123456789	
.-	NEXT
192.168.0.10 10.0.	

i Note

Auxiliaries IP will only be asked when the Auxiliaries connection type is TCP/IP.

6.8.2.6 Auxiliaries port

Insert the port of the to be configured Auxiliaries. For example: "502"

Auxiliaries TCP port	
0123456789	
BACKSPACE	NEXT
502	

i Note

Auxiliaries port will only be asked when the Auxiliaries connection type is TCP/IP.

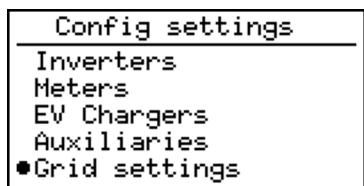
6.9 Grid settings

In this configuration power and current limits for the plant can be defined.

6.9.1 Grid settings configuration

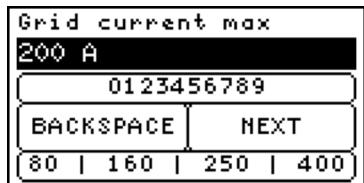
The following inputs are required to configure the grid settings:

- Grid current max
- Grid + power max
- Grid - power max
- Limit per 15 min



6.9.1.1 Grid current max

Enter the maximum allowed grid current for this plant. For example, the mains connection is 3x250 A, fill-in 250.

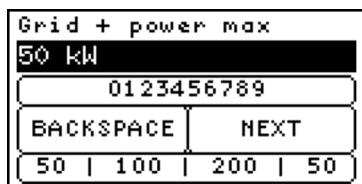


Tip

This is typically the value of the main fuse.

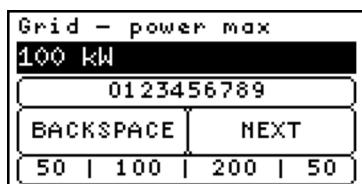
6.9.1.2 Grid + power max

Enter the maximum active power which might be consumed from the grid. For example: 50 kW.



6.9.1.3 Grid - power max

Enter the maximum active power which might be exported to the grid. For example: 100 kW. The Embion EMS Controller will implement export limitation controllers for configured solar inverters if the configured solar power exceeds the configured limit.



6.9.1.4 Limit per 15 min

This function is disabled by default. When enabled all power controllers (import and export) will use 15min values for control. The function can be enabled for only import or only export direction. This function is only of interest when the fysical grid connection is significantly larger than the contracted power. When enabled, the system will unlock import and export power limits to the fysical limit of the system, but will prevent the imported or exported energy to exceed the contracted power.

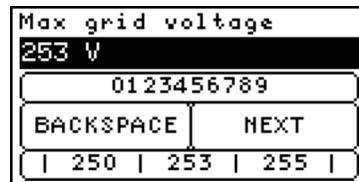
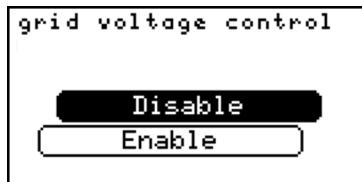
For a good prediction of the usage a base load percentage should be given. This is the expected load in the system when all controllable systems are off. The expected energy consumption is reserved during the 15 minutes.

 **Warning**

Only use this function when the installation is capable of handling larger powers. If function is not clear, disable the feature!

6.10 Grid voltage control

The grid voltage control can be enabled to apply an active power controller in the Embion EMS Controller, regulating the measured grid voltage. The maximum line-neutral grid phase voltage is determined, if this voltage is larger than the configured maximum grid voltage, the inverter active power setpoint is reduced (Using a fixed PI controller). This will limit the active power and therefore lower the grid voltage.



Tip

The grid voltage measured by the inverter is likely to be higher than the voltage at the grid entrance or grid meter location. Hence, it is important to ensure that the maximum allowable grid voltage set in the inverter is higher than the configured maximum grid voltage in the Embion EMS Controller.

Warning

The P1 DSMR 4 protocol does not support phase voltage measurement. Therefore it is not possible to use grid voltage control when the grid meter is a P1 DSMR 4 energy meter.

6.11 Active power control

By default, the configured number and power of the solar panels, together with the configured maximum grid return power and maximum grid current let the Embion EMS Controller decide if an active power or current controller is required for the configuration. By default an plant control active power controller is also implemented. As user this default configuration can be altered, by changing the Active power control setting.

- Auto: (Default) depending on the configured limits an active power and/or current controller is implemented
- Force disable: all power controllers are disabled! Plant control, export limit control and grid voltage control is not possible. Be careful using this configuration!

- Force enable: enables the plant control, active power and grid current controller independent of the amount of solar power configured. Using this setting the maximum reduction value can be limited by the user.



! **Warning**

Setting the “Force disable” option will disable all active power controllers. There will be no grid current, power or voltage control done by the Embion EMS Controller. Also power control via plant control is disabled! Therefore inverters will not be limited when EPEX price control is active.

6.11.1 Safety margin

The “Safety margin” is 0 by default. It sets a positive offset to the configured grid return power. An example: a plant is not allowed to return power to the grid (negative grid power), so the maximum grid return power is set to 0. Due to loads which are switched off, some energy will still be returned to the grid. To prevent this, a safety margin can be configured. The Embion EMS Controller will offset the control setpoint with the safety margin. If the grid return power is set to 0kW and the safety margin is set to 5kW, the Embion EMS Controller will limit PV and battery power in such way the grid power is tried to be 5kW. When a load of 4kW is suddenly switched off, the grid power will still be positive and the Embion EMS Controller will correct for it.

! **Warning**

Only utilize the safety margin option in instances where there is a highly stringent return-to-grid policy. Utilizing the safety margin will lead to an increase in total grid power consumption and consequently, costs.

6.11.2 Control speed

The control speed is set to Normal by default. This setting determines the overall speed at which the internal control loops operate and the assets are controlled. If a faster response is desired, the speed can be increased.

 **Warning**

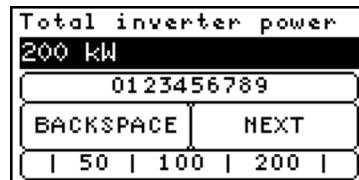
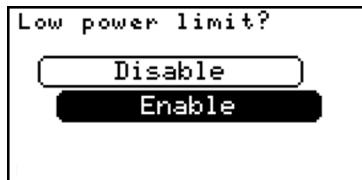
When using the Fast option, it is important that all assets have sufficient response speed and are able to follow the setpoints within a maximum of 1 second. Assets that do not meet this requirement will destabilize the system!

6.11.3 Low power limit

The “low power limit” is disabled by default. This function can be enabled if the maximum generated solar power should be continuously controlled (even when the grid power or current is not close to the limit). This function prevents large peaks when solar power suddenly increases but also increases the inverter ramp-up time. Enabling this option results in significantly lower peak powers. The total configured inverter power is required to correctly use this function. The function can't correctly operate when not all inverters are active, if one of the inverters is not active, the function will temporary be disabled.

 **Tip**

For systems with PV peak-shaving for a limited mains connection, it is advised to enable the low power limit option. This prevents high peak feeding currents which may trip the mains fuse.



6.11.4 Total PV inverter power

(This value is only required when Low power limit is enabled). The sum of the total nominal PV inverter power. Inverter which are only used as battery converter should not be included in the sum.

6.11.5 Set minimum power limit to 5%

Default disabled When enabled the minimum reduction value send to all PV inverters is 5%. This results in all PV inverters to always generate 5% of their nominal power. Some brand or installations require this feature.

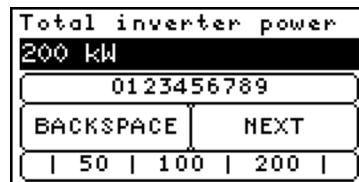
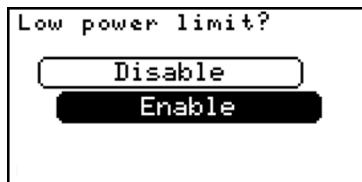
6.11.6 Force battery charge before PV reduction

Has only effect when battery is configured and Low power limit is disabled. If set enabled the Embion EMS Controller will first try to maximise battery charging power, before reducing the PV power. This will however effect the response time in cases where one or more battery systems are not capable of charging.

6.11.7 Maximum power limit

Setting the maximum power limit to less than 100% will consistently restrict the inverters maximum output power to the configured percentage. Consequently, the maximum output power of the inverters will never be attained, even if the grid current and grid negative power have not yet reached their limits yet.

For Auto and Force enable the following options are available to configure low power limit:



6.11.7.1 Allow PV for import limit

Default disabled. Enabling this function allows the PV limit controller to further increase PV power when the import limit is reached. Therefore the PV power could still be generated while the system is in MIN generation, only to prevent the import limit to be exceeded. PV is controlled with PRIO1, other priorities are processed first before PV power is increased.

6.11.7.2 Charge battery with grid return power

When this function is enabled, the battery charge power is increased when the mains active power becomes negative. Therefore the returned grid power could be used for charging the battery. It is advised to disable the "Allow automatic charge" option in the inverter group.

6.11.8 Compenstate own usage with battery

When this function is enabled the battery will be discharged when power is consumed from the grid, to prevent consumption from the grid. The minimum SoC to which the battery can be discharged is set per battery inverter.

6.12 Arc detection

This configuration will define the external arc detection settings. By default external arc detection is disabled. Keep in mind, any GPIO used to connect to the external arc detection should be true when no arc is detected!

6.12.1 Arc detection configuration

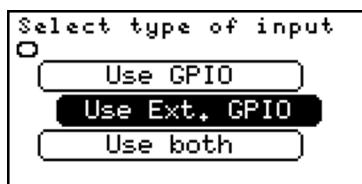
The following inputs are required to complete Arc detection configuration:

- Input type
- Minimum PAC
- Inverter address

6.12.1.1 Input type

Select the input type for Arc detection, options are:

- Deactivate
- GPIO (use onboard GPIO for max 2 inverters)
- Ext. GPIO (use Modbus GPIO modules for multiple external arc detections)
- Both (Use as well the internal GPIO as external GPIO modules)



The deactivate option will deactivate arc detection, even if the Arc detection strategy is selected. Arc detection is deactivated by default.

6.12.2 Minimum PAC

Enter the minimum PAC (Inverter AC power) required per inverter for an arc detection. If the AC power of the inverter is not at least as high as Minimum PAC, while a detection is done, the detection is neglected.

Minimum PAC for arc	
100 W	
0123456789	
BACKSPACE	NEXT
50 100 200 300	

6.12.3 Inverter address

This menu is only visible if the “Both” option is selected. It allows the user to select the one or two inverter addresses controlled by the internal GPIO. The other addresses will be logically (from low to high) mapped to the external GPIO modules. For example, if 5 inverters are configured, 1,2,3,4,5 and only 2 external GPIO modules are configured and “Inverter address” is set to 3,4: The first GPIO modules is connected to inverter 1, the second GPIO module to inverter 2 and GPI1 is connected to inverter 3, GPI2 to 4. Inverter 5 has no arc detection connected. Setting the “Inverter address” to 1 in this situation connects inverter 1 to GPI1 and inverter 2 to external GPIO 1 and inverter 3 to external GPIO 2.

inv addr for GPIO	
10	
0123456789	
-,	NEXT
1-2 1-3 1-4 1,	

6.12.3.1 Connecting the external arc detection

When connecting the external arc detection please check the following items:

- Make sure the arc detection is not latched on detection.
- Make sure the GPIO of the Embion EMS Controller or input on the external GPIO are HIGH when no detection is done and LOW when a detection is done.
- Check the functionality of the external arc detection
- Check the functionality of the configured Embion EMS Controller, check if the correct inverter is turned-off when a detection is done.

6.13 GPIO control

Allows the user to add multiple rules for the onboard or external GPIO. Actions can be triggered depending on the GPI (General Purpose Input) state or states can trigger GPO (General Purpose Output). The Embion EMS Controller has two GPI and two GPO onboard. It is possible to configure 4 independent GROUP states, which can be linked to the digital output of external IO modules.

Each rule added to the list can only handle one state, for example the following setting: "IN1 is HIGH then set Min gen set to TRUE" Will limit the generation when input1 becomes HIGH. After input1 becomes LOW again, no new action is triggered, so the system will stay in Min gen. To return to normal operation when input1 is low again, the following rule should also be added: "IN1 is LOW then set Min gen set to FALSE"

It is possible to use the following variables to define triggers:

- contr. gen. (Control Generation) which is the generation state which can be remotely set to MIN, NOM or MAX (default NOM)
- contr. cons. (Control Consumption) which is de consumption state which can be remotely set to MIN, NOM or MAX (default NOM)
- Psolar (System Solar power) which is the actual solar power (sum of solar power of all inverters), value is set in kW
- Pgrid (System grid power) which is the grid meter active power, value is set in kW
- Reduction which is the actual solar inverter limit value, 0 means solar is reduced to 0% of nominal, and 100 means solar is unlimited
- Battery SoC which is the (weighted) average of the connected battery SoC values, value is set in %
- Summed load meters which is the sum of the active power of all the load meters, value is set in kW
- Pbattery the total battery power in the system, value is set in kW
- PRIO the actual load prio 0-10, where 0 means all loads off and generate to reach the import limit, value is set between 0 and 10

As example, when GPO1 needs to be enabled when the grid power is -10kW and disabled when the grid power is 0kW the following rule can be set:

Group: GPO1 ON (give the action a logic name) Select GPIO: GPO1 (the rule will control GPO1) Set to: TRUE (The rule will enable GPO1) When: Pgrid (select grid power) Operator: < (When greater than) Value: value (select free value input) Set value: -10 (set the value to -10kW)

Group: GPO1 OFF (give the action a logic name) Select GPIO: GPO1 (the rule will control GPO1) Set to: FALSE (The rule will enable GPO1) When: Pgrid (select grid power) Operator: > (When greater than) Value: value (select free value input) Set value: 0 (set the value to 0kW)

As example, when GPO1 needs to be enabled when control generation is set to MIN remotely:

Group: GPO1 ON (give the action a logic name) Select GPIO: GPO1 (the rule will control GPO1) Set to: TRUE (The rule will enable GPO1) When: contr. gen (Select control generation as this value is changed remotely) Operator: == (Equal to) Value: min (MIN, to set GPO1 to true when contr. gen. is set to MIN)

Group: GPO1 OFF (give the action a logic name) Select GPIO: GPO1 (the rule will control GPO1) Set to: FALSE (The rule will disable GPO1) When: contr. gen (Select control generation as this value is changed remotely) Operator: != (Not equal to) Value: min (MIN, to set GPO1 to false when contr. gen. is NOT set to MIN)

 Tip

The activation and deactivation of a GPO or Group is always done in two separate actions. Multiple actions can be created which all enable or disable the GPO.

6.14 Cascade

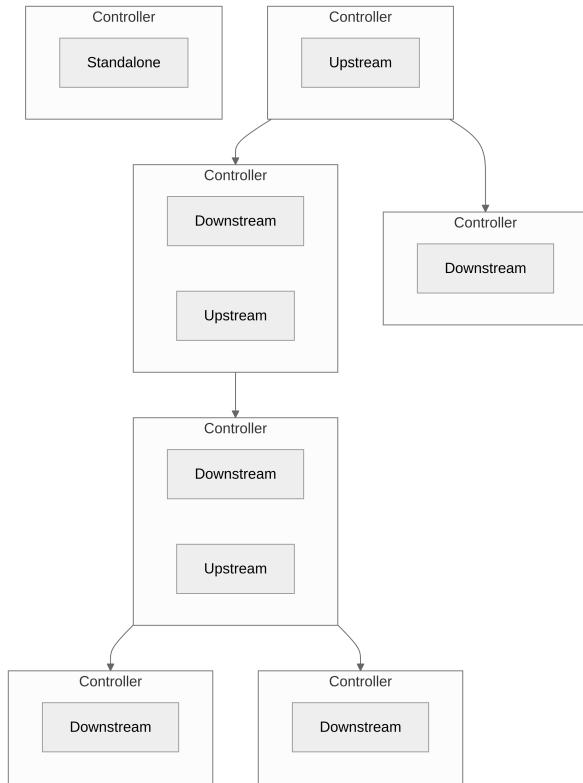
 Note

The cascade functionality is only available for Embion EMS Controllers.

Cascade setup is used to control multiple controllers in a cascade.

Upstream is the commanding controller, while Downstream is the controlled controller.

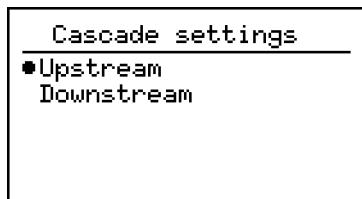
The upstream controller will control the downstream controller(s) and will be used to set the active power setpoint for the downstream controller(s).



6.14.1 Cascade Setup

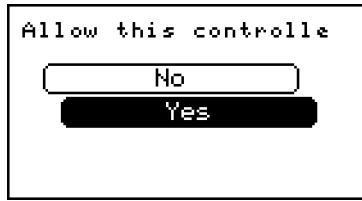
The downstream controller(s) will be controlled by the upstream controller. The downstream controller(s) will not be able to set the active power setpoint, this will be done by the upstream controller.

The upstream is the main controller in the cascade. It will control the downstream controllers and will be used to set the active power setpoint for the downstream controllers.



6.14.1.1 Upstream

To allow a controller to be used as downstream controller, enable upstream in the configuration. This will allow the controller to be used as a controller in a cascade.



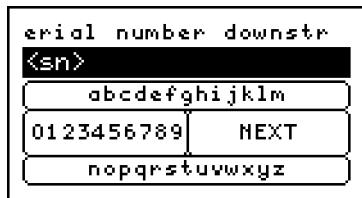
6.14.1.2 Downstream

To control the downstream controller(s), add the downstream controller(s) to the configuration. The following settings are required to configure the downstream controller(s):

- Serial number downstream controller
- IP address downstream controller
- Maximum battery power of downstream controller (and all underlying controllers)
- Maximum battery energy of downstream controller (and all underlying controllers)
- Maximum PV power of downstream controller (and all underlying controllers)
- Maximum EV power of downstream controller (and all underlying controllers)

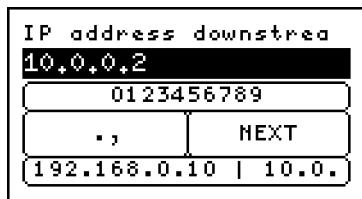
6.14.1.2.1 Serial number downstream controller

The serial number of the downstream controller(s) is required to identify the downstream controller(s) in the cascade.



6.14.1.2.2 IP address downstream controller

The IP address of the downstream controller(s) is required to identify the downstream controller(s) in the cascade.



6.14.1.2.3 Maximum battery power of downstream controller (and all underlying controllers)

The maximum battery power of the downstream controller(s) is required to set the active power setpoint for the downstream controller(s). The maximum battery power of the downstream controller(s) is the sum of the maximum battery power of all underlying controllers. Set to 0 when no battery is connected to the downstream controller(s).

maximum battery power	
0 kW	
0123456789	
BACKSPACE	NEXT
0 50 100 200	

6.14.1.2.4 Maximum battery energy of downstream controller (and all underlying controllers)

The maximum battery energy of the downstream controller(s) is required to set the active power setpoint for the downstream controller(s). The maximum battery energy of the downstream controller(s) is the sum of the maximum battery energy of all underlying controllers. Set to 0 when no battery is connected to the downstream controller(s).

maximum battery energy	
0 kWh	
0123456789	
BACKSPACE	NEXT
10 50 75 100	

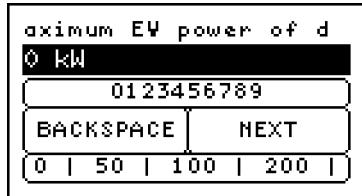
6.14.1.2.5 Maximum PV power of downstream controller (and all underlying controllers)

The maximum PV power of the downstream controller(s) is required to set the active power setpoint for the downstream controller(s). The maximum PV power of the downstream controller(s) is the sum of the maximum PV power of all underlying controllers. Set to 0 when no PV is connected to the downstream controller(s).

maximum PV power of	
0 kWP	
0123456789	
BACKSPACE	NEXT
200 300 400 45	

6.14.1.2.6 Maximum EV power of downstream controller (and all underlying controllers)

The maximum EV power of the downstream controller(s) is required to set the active power setpoint for the downstream controller(s). The maximum EV power of the downstream controller(s) is the sum of the maximum EV power of all underlying controllers. Set to 0 when no EV chargers are connected to the downstream controller(s).



6.15 RTI

i Note

The RTI functionality is only available for Embion EMS Controllers.

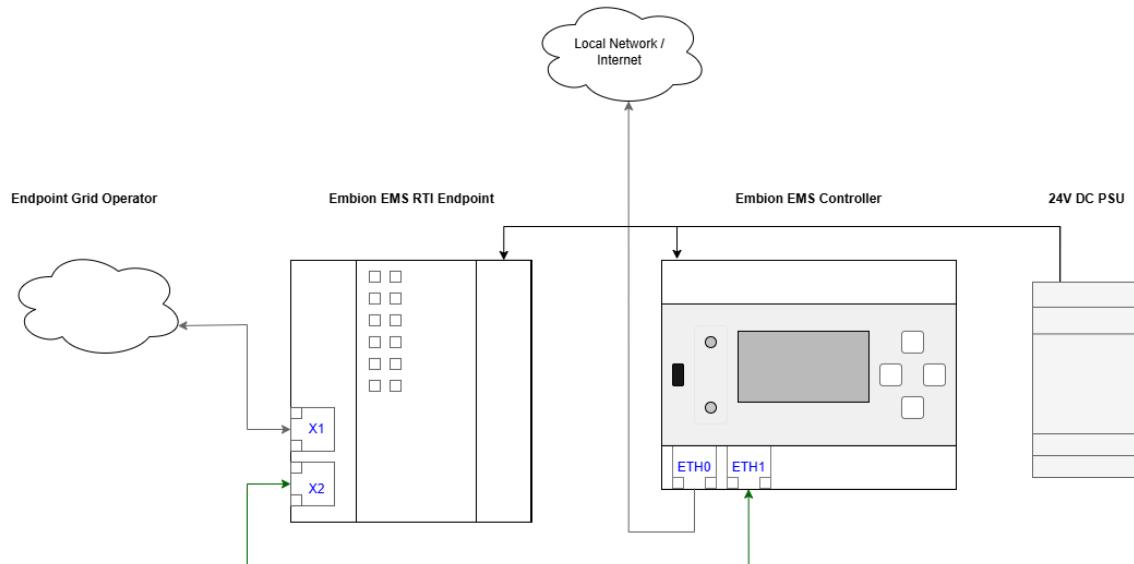
RTI is used to receive limits from the grid operator.

6.15.1 RTI hardware setup

When using RTI, two extra devices are required:

- Embion EMS RTI Endpoint
- Endpoint grid operator

Contact your grid operator to obtain the Endpoint grid operator.

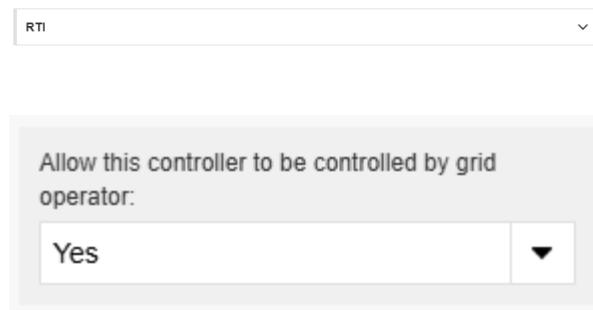


Connect the ETH1 port of the Embion EMS Controller to the X2 port of the Embion EMS RTI Endpoint using the provided, green cable. The ETH0 port of the Embion EMS Controller can be used regularly.

The X1 port of the Embion EMS RTI Endpoint should be connected to the Endpoint grid operator. Use a standard Ethernet cable directly between the two ports. It is not possible to use a (local) network between the Embion EMS RTI Endpoint and the Endpoint grid operator.

6.15.2 RTI configuration setup

To enable RTI, enable control of the grid operator in the settings menu.

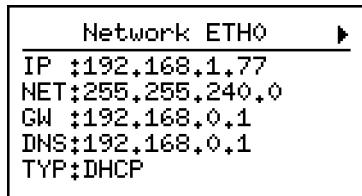


7 Device settings

This part of the manual will describe all device settings and configurations.

7.1 ETH0 settings

Shows the actual status of the ETH0 port, and allows user to change port IP configuration.



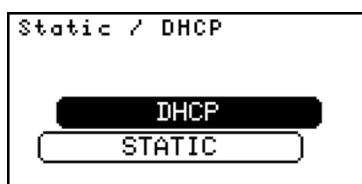
7.1.1 ETH0 Setup



7.1.1.1 ETH0 Type

Select the type of ETH0 connection, options are:

- DHCP
- STATIC



i Note

When DHCP is selected as network type for ETH0, no other settings are needed for configuration. If Static is selected as ETH0 network type, other settings below are

needed.

7.1.1.2 ETH0 IP Address

Enter the IP address of the ETH0 network, for example: "192.168.0.10"

ETH0 IP address	
192.168.0.10	
0123456789	
.-	NEXT
192.168.0.10 10.0.	

7.1.1.3 ETH0 Gateway IP address

Enter the IP address of the network default gateway, for example: "192.168.0.1".

This field can be left empty when there is no default gateway for this connection (and therefore no internet connection through this port).

ETH0 Gateway address	
192.168.0.1	
0123456789	
.-	NEXT
192.168.0.10 10.0.	

7.1.1.4 ETH0 Netmask

Enter the network Netmask, for example: "255.255.255.0".

ETH0 Netmask	
255.255.255.0	
0123456789	
.-	NEXT
255.255.255.0	

7.1.1.5 ETH0 DNS

Enter the DNS setting for ETH0, for example: "8.8.8.8".

This field can be left empty when there is no DNS required.

ETH0 DNS	
8.8.8.8	
0123456789	
.	NEXT
8.8.8.8	4.4.4.4

7.2 ETH1 settings

Shows the actual status of the ETH1 port, and allows user to change port IP configuration.

Network ETH0	▶
IP: 192.168.1.77	
NET: 255.255.240.0	
GW: 192.168.0.1	
DNS: 192.168.0.1	
TYP: DHCP	

7.2.1 ETH1 Setup

Network ETH1 setti
•ETH1 Setup

7.2.1.1 ETH1 Type

Select the type of ETH1 connection, options are:

- DHCP
- STATIC

Static / DHCP
DHCP
STATIC

i Note

When DHCP is selected as network type for ETH1, no other settings are needed for configuration. If Static is selected as ETH1 network type, other settings below are needed.

7.2.1.2 ETH1 IP Address

Enter the IP address of the ETH1 network, for example: "192.168.0.10"

ETH1 IP address	
192.168.0.10	
0123456789	
.-	NEXT
192.168.0.10 10.0.	

7.2.1.3 ETH1 Gateway IP address

Enter the IP address of the network default gateway, for example: "192.168.0.1".

This field can be left empty when there is no default gateway for this connection (and therefore no internet connection through this port).

ETH1 Gateway address	
192.168.0.1	
0123456789	
.-	NEXT
192.168.0.10 10.0.	

7.2.1.4 ETH1 Netmask

Enter the ETH1 Netmask, for example: "255.255.255.0".

ETH1 Netmask	
255.255.255.0	
0123456789	
.	NEXT
255.255.255.0	

7.2.1.5 ETH1 DNS

Enter the DNS setting for ETH0, for example: "8.8.8.8".

This field can be left empty when there is no DNS required.

ETH1 DNS	
8.8.8.8	
0123456789	
.	NEXT
8.8.8.8	4.4.4.4

7.3 Wi-Fi settings

Shows the actual status of the Wi-Fi connection, and allows user to configure Wi-Fi

Network Wi-Fi	▶
SSID: Embion B.V.	
IP : 192.168.1.194	
NET : 255.255.240.0	
GW : 192.168.0.1	
TYP : DHCP	

7.3.1 Wi-Fi Setup

Network Wi-Fi settin
•Wi-Fi Setup

7.3.1.1 Wi-Fi Enable

Enable or disable Wi-Fi

Enable Wi-Fi?
No
Yes

7.3.1.2 Wi-Fi Network

The device will ask to search for networks. A search will take a few seconds after which a network can be selected from a list.



7.3.1.3 Wi-Fi Password

Enter the network password and apply the Wi-Fi settings.



i Note

The device only supports the WPA2 security standard and uses DHCP for automatic configuration.

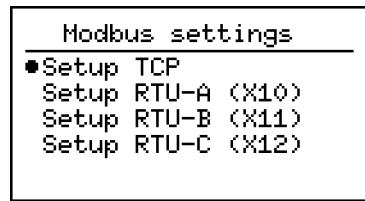
! Note

For optimal use it is recommended to use the ethernet connection instead of Wi-Fi. Using Wi-Fi is dependent on the quality of the network and might result in stability and performance issues.

7.4 Modbus settings

This explains the RTU setup for:

- TCP
- RTU-A (X10)
- RTU-B (X11)
- RTU-C (X12)



7.4.1 TCP configuration

7.4.1.1 Client / Server settings

To enable / disable Modbus TCP server on the Embion EMS Controller TCP, select the desired setting:

- Client (default)
- Client & Server

The Modbus client is used to communicate with the configured assets. The Modbus TCP server is used to readout or control to the Embion EMS Controller from an external controller with Modbus client support. Ask your sales representative for the actual Modbus register layout.



Note

When 'Client & Server' is selected as setting, no other settings are needed for the Modbus TCP configuration. If 'Client' is selected, other settings below are needed.

7.4.1.2 Interface

Select to desired Modbus interface. For now, only one interface is available.



7.4.1.3 TCP Port

Enter the TCP port for the Modbus Server TCP connection. The port is used to host the Modbus server on the ip address of the Embion EMS Controller. It is recommended to use port '502'.

TCP Server IP port (
502			
0123456789			
BACKSPACE	NEXT		
50	100	500	100

7.4.1.4 Unit ID

Enter the Modbus unit id for the Modbus Server TCP connection. The unit ID is used to identify the Embion EMS Controller in the Modbus network. Valid range is 1-247, as defined in the Modbus protocol.

TCP Server Modbus Un				
2				
0123456789				
BACKSPACE	NEXT			
1	50	100	500	1

7.4.2 RTU configuration

The following inputs are required to complete RTU configuration:

- Baudrate
- Parity
- Databits
- Stopbits

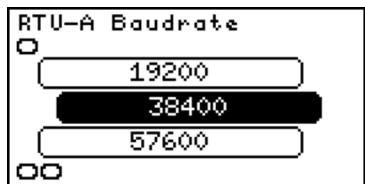
The default port configuration is 9600 8N1.

7.4.2.1 Baudrate

Select the baudrate for the RTU connector, options are:

- 9600
- 19200
- 38400

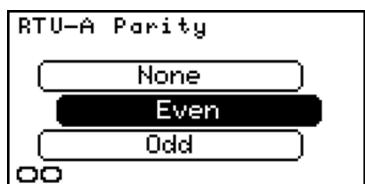
- 57600
- 115200
- 230400



7.4.2.2 Parity

Select the parity for the RTU connector, options are:

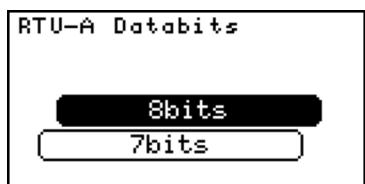
- None
- Even
- Odd



7.4.2.3 Databits

Select the databits for the RTU connector, options are:

- 8 bits
- 7 bits



7.4.2.4 Stopbits

Select the stopbits for the RTU connector, options are:

- 1 bit

- 2 bits



7.5 GPIO settings

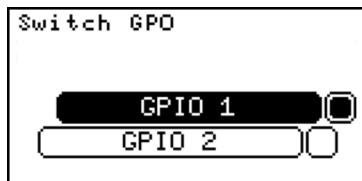
The GPIO page shows the actual status of the input ports.

GPIO	▶
GPIO 1	↑high
GPIO 2	↓low

GPIO settings
•Control GPO

7.5.1 Control GPO

This menu allows the user to directly control the two output ports on the Embion EMS Controller.



⚠ Warning

Forcing the GPO state can counteract the intended function!

7.6 System settings

This page shows actual connection status of the Embion EMS Controller.

- Internet, yes if the device was able to ping to an external ip.
- HUB, paired if the user has already paired the device to the HUB.
- Support, shows the support ID when support is enabled.

System settings contains

- Display setup (Dim brightness and Contrast settings)
- Language selection

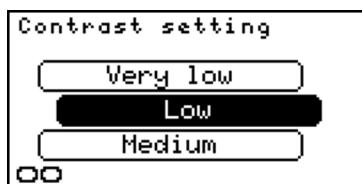


7.6.1 Display setup (Dim brightness)



Select the low level of the backlight intensity. The Embion EMS Controller will reduce the backlight to the configured intensity when the buttons are not pressed for a while.

7.6.2 Display setup (Contrast settings)



Configures the display's contrast. By hovering over the options, the display contrast will change to the selected intensity.

7.6.3 Language selection

Configures the system language for all status and configuration pages.

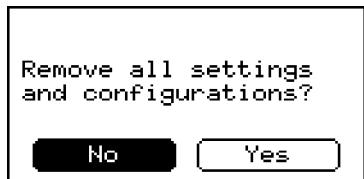


7.6.4 Data upload interval

A upload interval of 1 (default), 5 or 15 minutes can be configured for asset data from EMS to HUB. This can be helpful in situations where there is a data limit like with a 4G modem. Data uploaded at 5 or 15 minute interval can't be restored to a smaller interval.

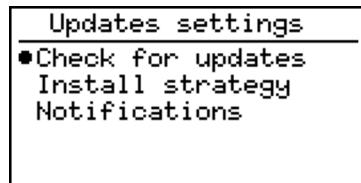
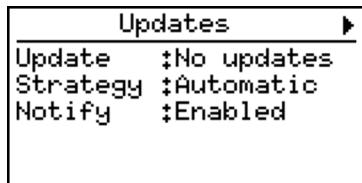
7.6.5 Factory Reset

Performs a factory reset of the device. Be aware that this process will delete all user settings and configurations, returning the device to its original state. The device will ask for confirmation twice.



After confirmation, the device will reboot and reset. This will take less than a minute during which nothing is shown on the display and both status LEDs will be off. Once finished, you will be presented with the First Time Use wizard to set up the device again. Note that any license(s) will remain unaffected by the reset and will not be removed during this process.

7.7 Update settings



7.7.1 Check for updates

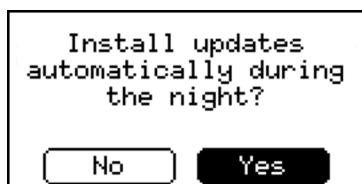
Manually verify if any software updates are available. The Embion EMS Controller should be connected to the internet to check for new updates.



7.7.2 Install strategy

Selects the strategy to run updates. Two options are available:

- Automatically: Embion EMS Controller will automatically download and install available updates at night.
- Manual: If enabled a notification is shown when an update is available. The device will not automatically install updates.



7.7.3 Notifications

Turn on or turn off update notifications on the Embion EMS Controller.



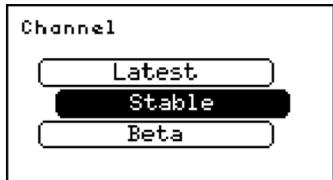
7.7.4 Channel

Select the active update channel.

- Latest: (default) get the latest official releases
- Stable: Only receive stable updates (version have already been tested for multiple weeks till months in a production environment)
- Beta: Receive Beta versions (no official release!)

 **Warning**

The Beta channel is not recommended for devices in a production environment. Releases in the Beta channel are still in the testing phase. There is no warranty for the functionality of the software.



7.8 Plant control

This page shows the actual plant control status. When no plant control command is currently running the status is "idle" and all items contain "-". When a plant control command is remotely given the status becomes "active" and the given command is shown at the right item.

When a plant control command is active the external LED turns blue.

When no plant control is active the plant control page shows a idle status:

Plant control	
Status	:Idle
Import limit	:-kW
Export limit	:-kW
Consumption	:-
Generation	:-

Plant control	
TTL	:--s
Remaining	:--s

When plant control is active the plant control page shows active status with the current control value. In this example the control item is generation to min with a Valid time (TTL) of 300 seconds.

Plant control	
Status	:Active
Import limit	:-kW
Export limit	:-kW
Consumption	:-
Generation	:min

Plant control	
TTL	:300s
Remaining	:300s

8 Appendix

8.1 Device specific instructions

8.1.1 Amtron 4you RTU configuration

This chapter describes how to setup the Amtron 4you RTU EV charger models. Consult the respective installation manual for detailed instructions on how to install the Amtron charger.

Required settings on the Embion EMS Controller:

- RTU settings: 57600 baud, no parity, 2 stopbits, 8 databits
- Use device ID 50 (set by default at the Amtron RTU device)

Required settings on the Amtron 4you (300 series):

- On DIP switch Bank S1 set (at least) nr. 4 and 5 to ON position

8.1.2 ABL eM4 configuration

Consult the respective installation manual for detailed instructions on how to install the eM4 charger.

ABL eM4 Extender devices are currently not supported.

ABL eM4 Extender devices are read via the Controller.

If all Extenders have been correctly added to the Controller, the total number of sockets (from the Controller and all Extenders combined) must be entered.

The software version of the eM4 Controller must be 2.2 or higher in order to be compatible with the Embion EMS Controller.

For single sockets ev chargers use only socket 1.

8.1.3 Aiswei configuration

The default ramp limit for reducing the inverter's power is too low to guarantee good performance.

This setting can be adjusted in the Solplanet App:

Inverter configuration -> Active power settings -> Active power increase/decrease gradient

It is recommended to set this to the maximum value.

8.1.4 EVBox

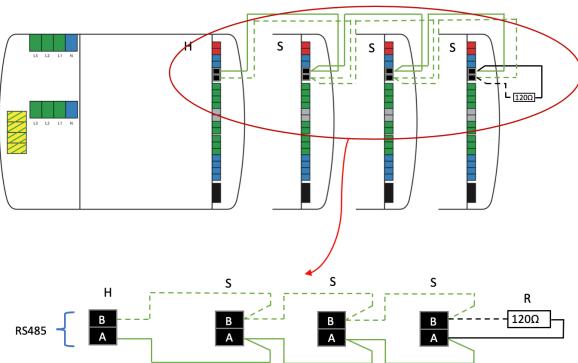
This chapter describe how to connect the RS485 cable to EVBox charging station models. Please consult the respective installation manual for detailed instructions on how to install the EVBox charger.

 **Warning**

For information on how to install and / or commission the EVBox charger, please refer to the official documentation provided by EVBox.

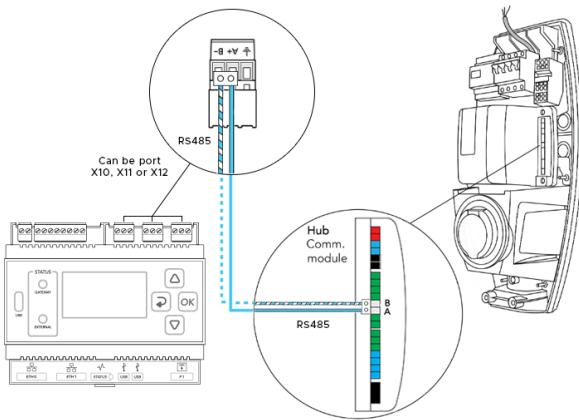
8.1.4.1 EVBox G4

To connect the G4, install an RS485 cable from the Embion EMS Controller to the RS485 port on the G4 HUB(s). The G4 Satellites should be connected to the G4 HUB following the instructions provided by EVBox.



EVBox G4 master / slave setup. Source: EVBox manual

The RS485 cable should be connected to the RS485 port on each G4 HUB as shown in the figure below.



EVBox G4 RS485 connector

8.1.5 Chint DTSU666 setup

There are two different versions of the Chint DTS666 with CT clamps in circulation. Some versions already account for the CT ratio, while others do not.

The most common variant already takes the CT ratio into account and is available with the Chint DTSU666 protocol.

If during setup the current and power do not match the display (too low values), choose the DTSU666 (Gain) type.

8.1.6 Flexicharge AC Charger Socket Settings

For the Flexicharge AC charger, socket 1 is available on port 502 and socket 2 on port 503. This port should not be changed, as it would disable support for socket 2.

If socket 2 is not available, please contact Flexicharge.

8.1.7 Solax X3 Ultra Hybrid - Firmware update

For the Solax X3 Ultra Hybrid there is a special firmware version. To update the inverter(s) to the correct firmware, please contact service.bnl@solaxpower.com



All products described in this document are owned by **Embion B.V.**

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